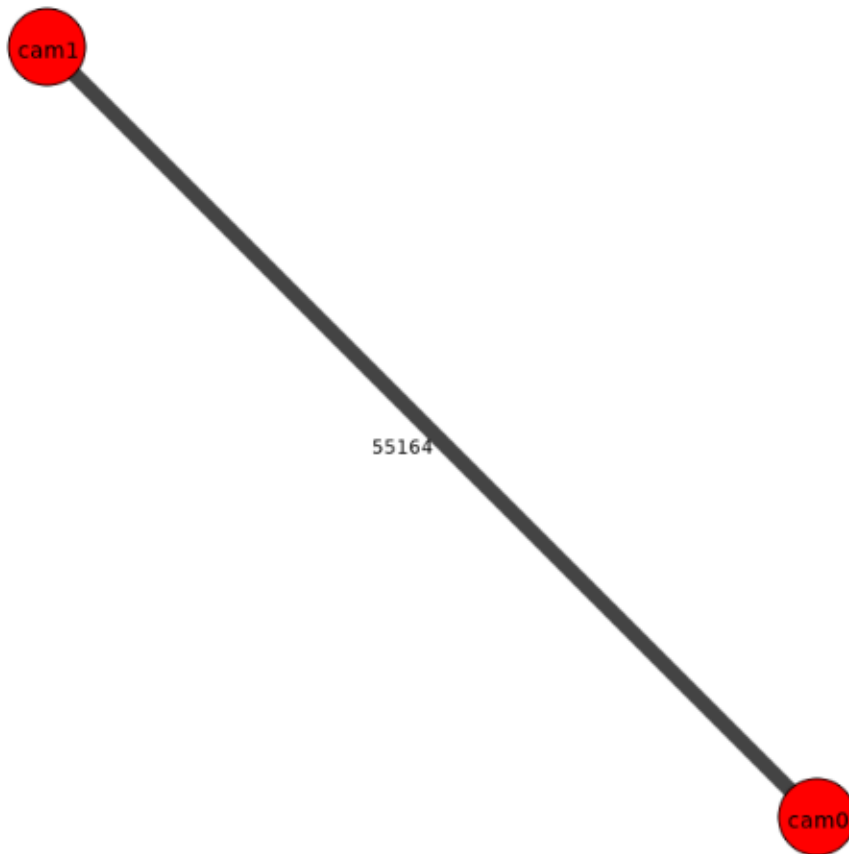
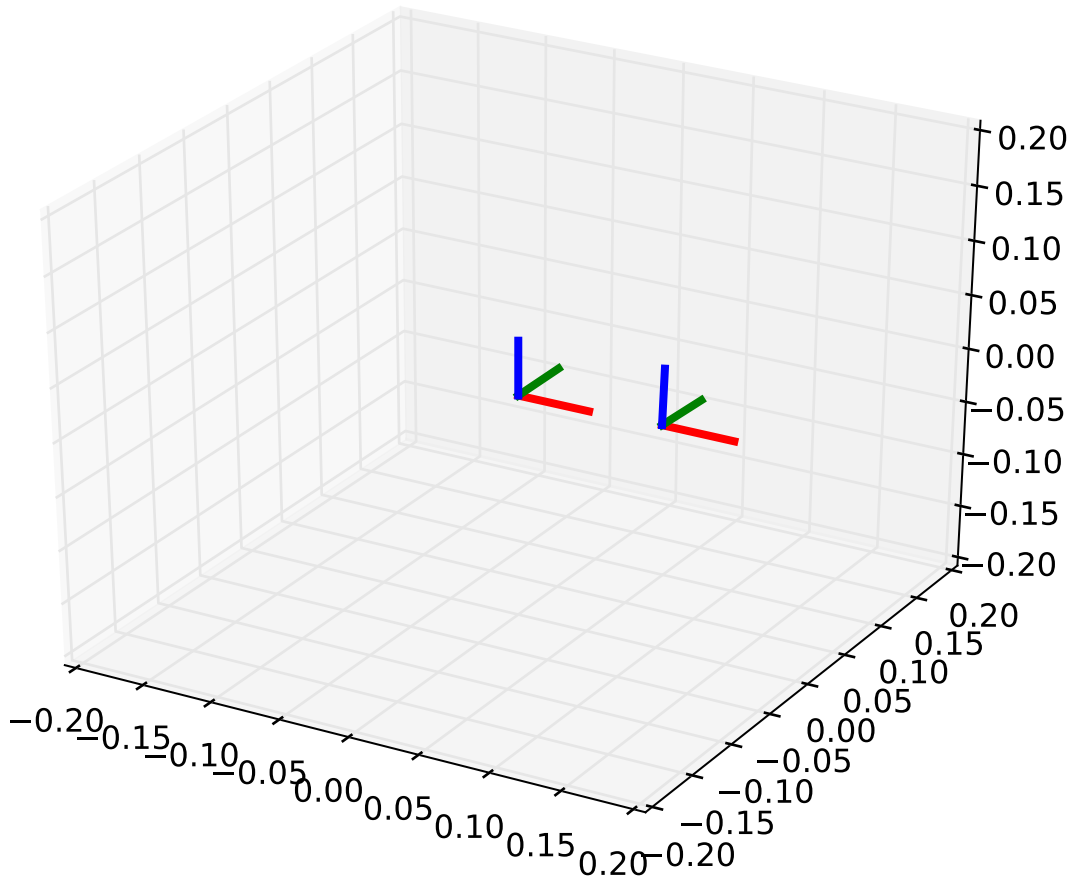


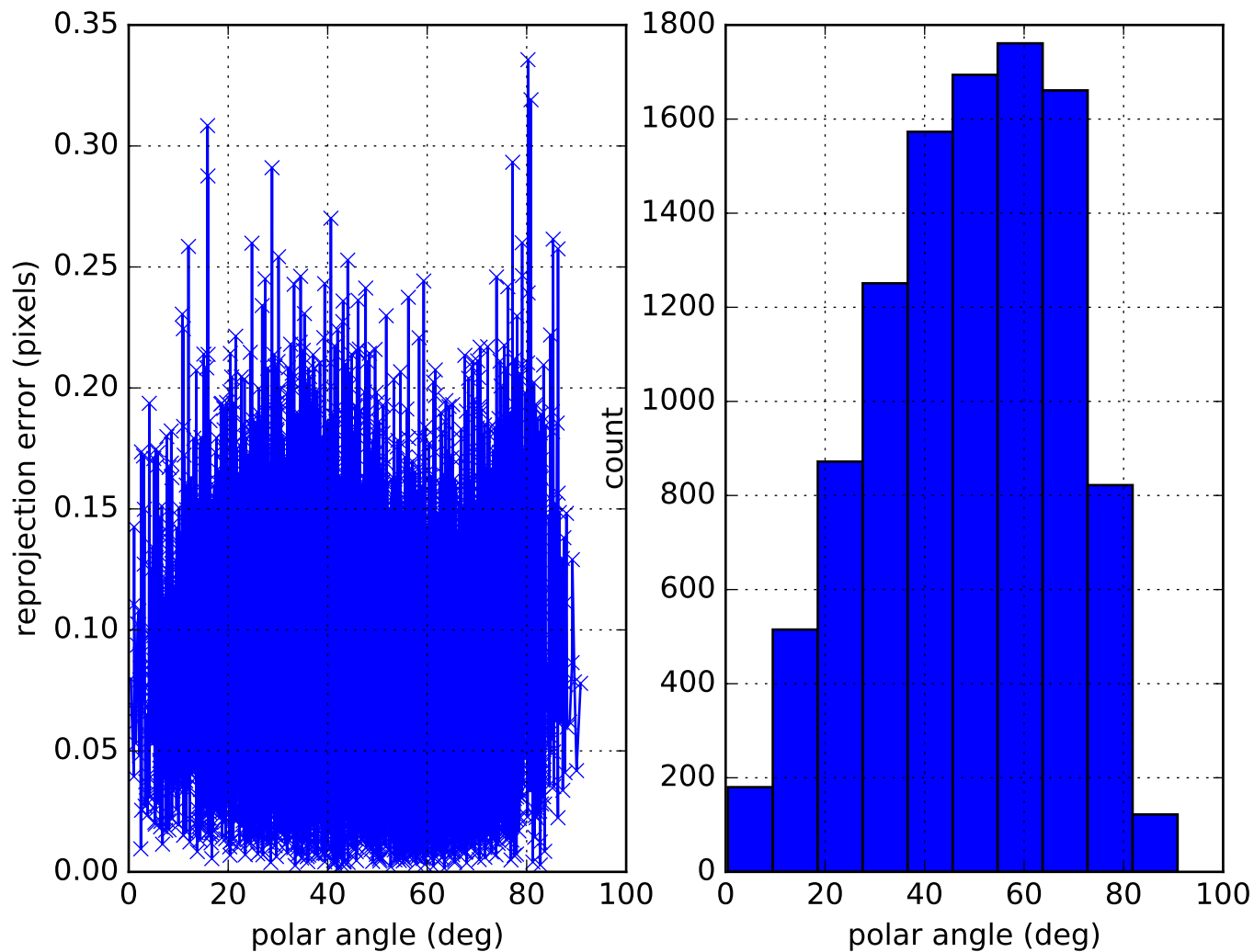
Inter-camera observations graph (edge weight=#mutual obs.)



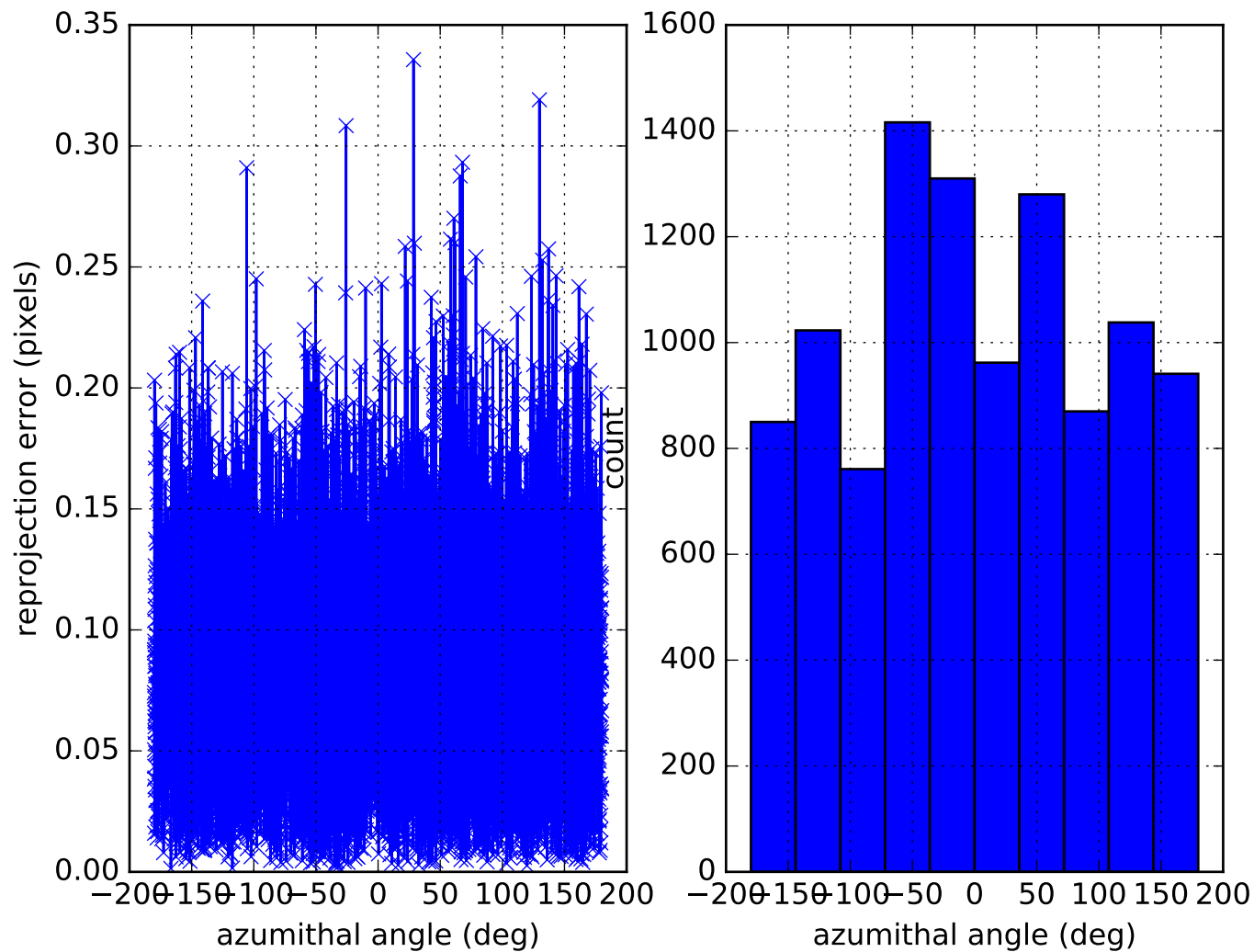
camera system



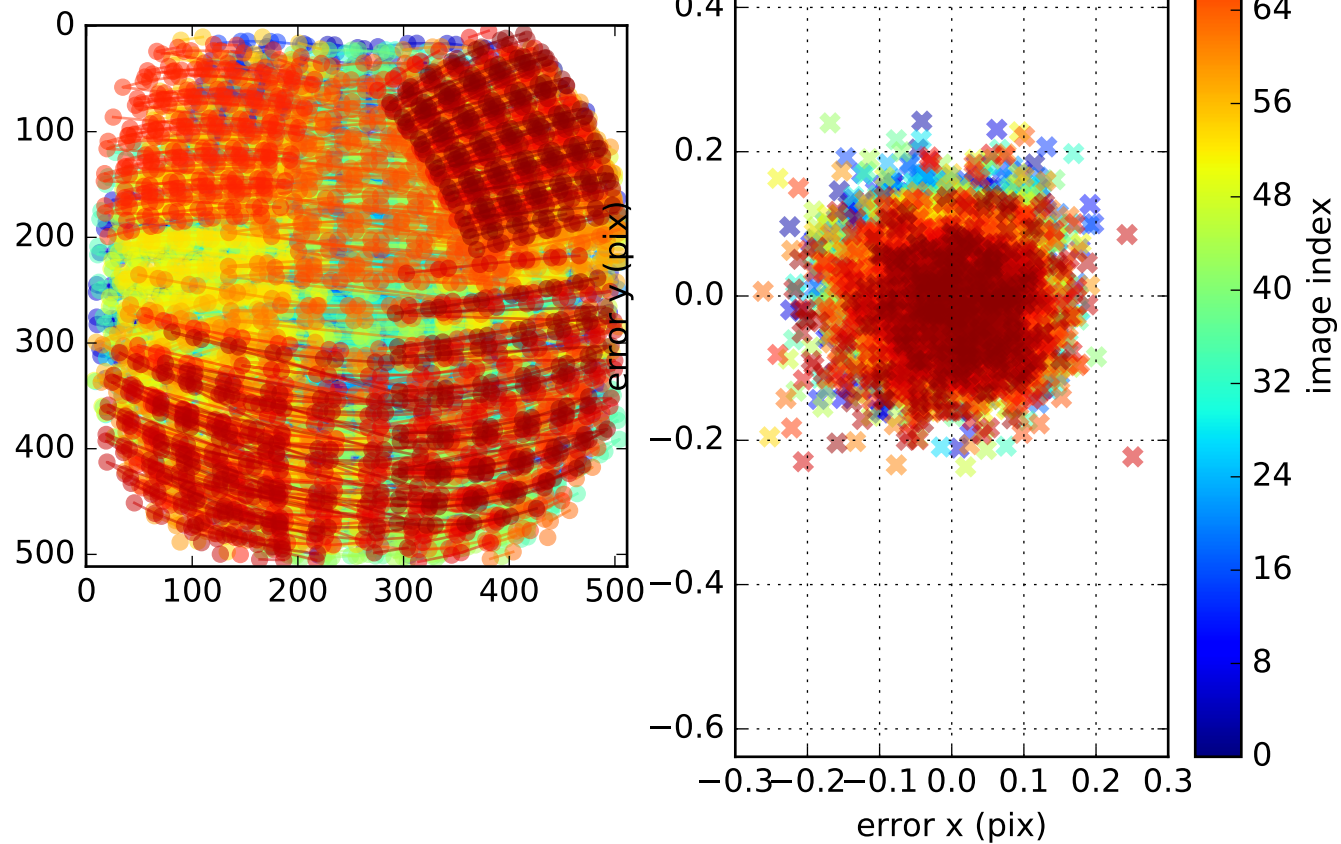
cam0: polar error



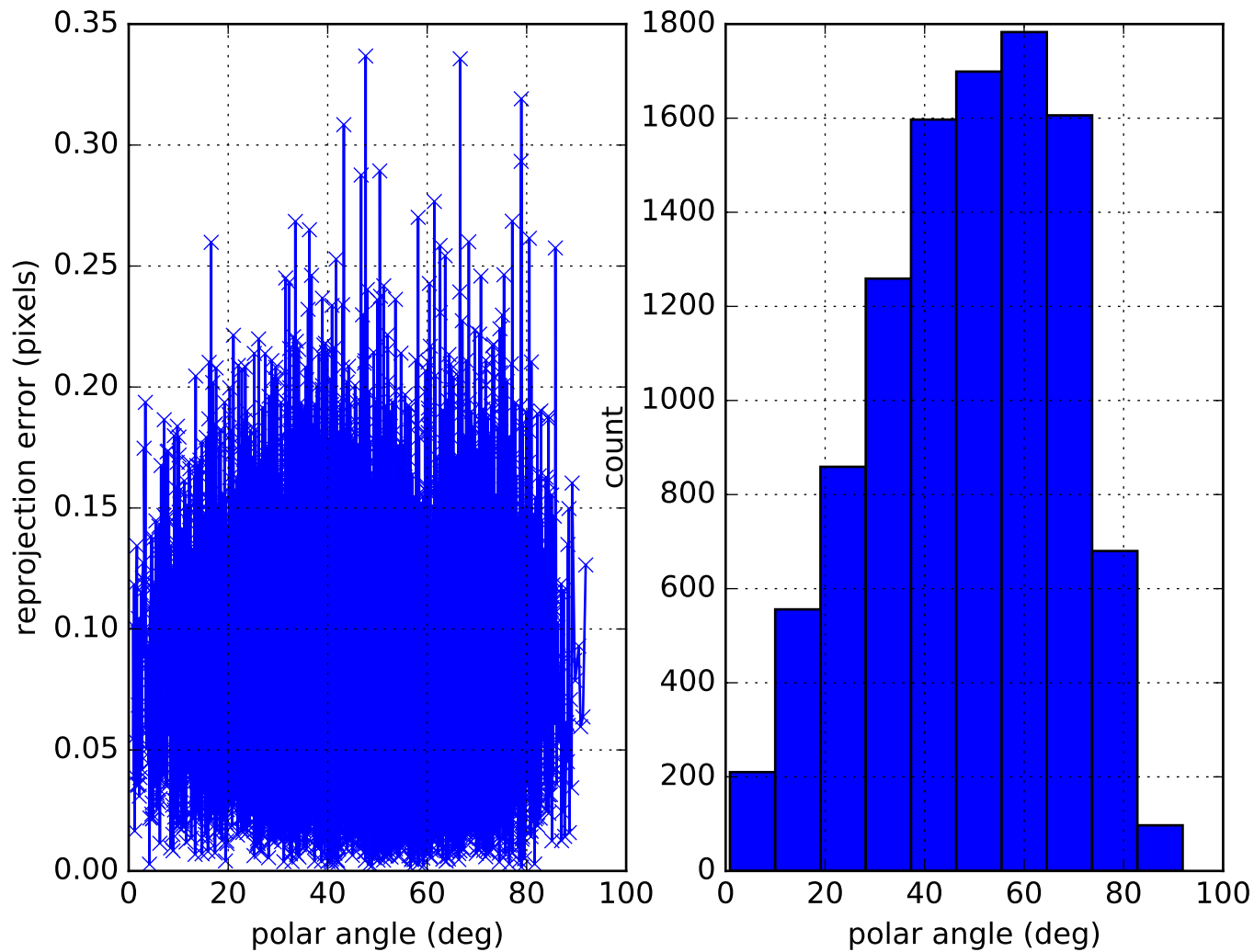
cam0: azimuthal error



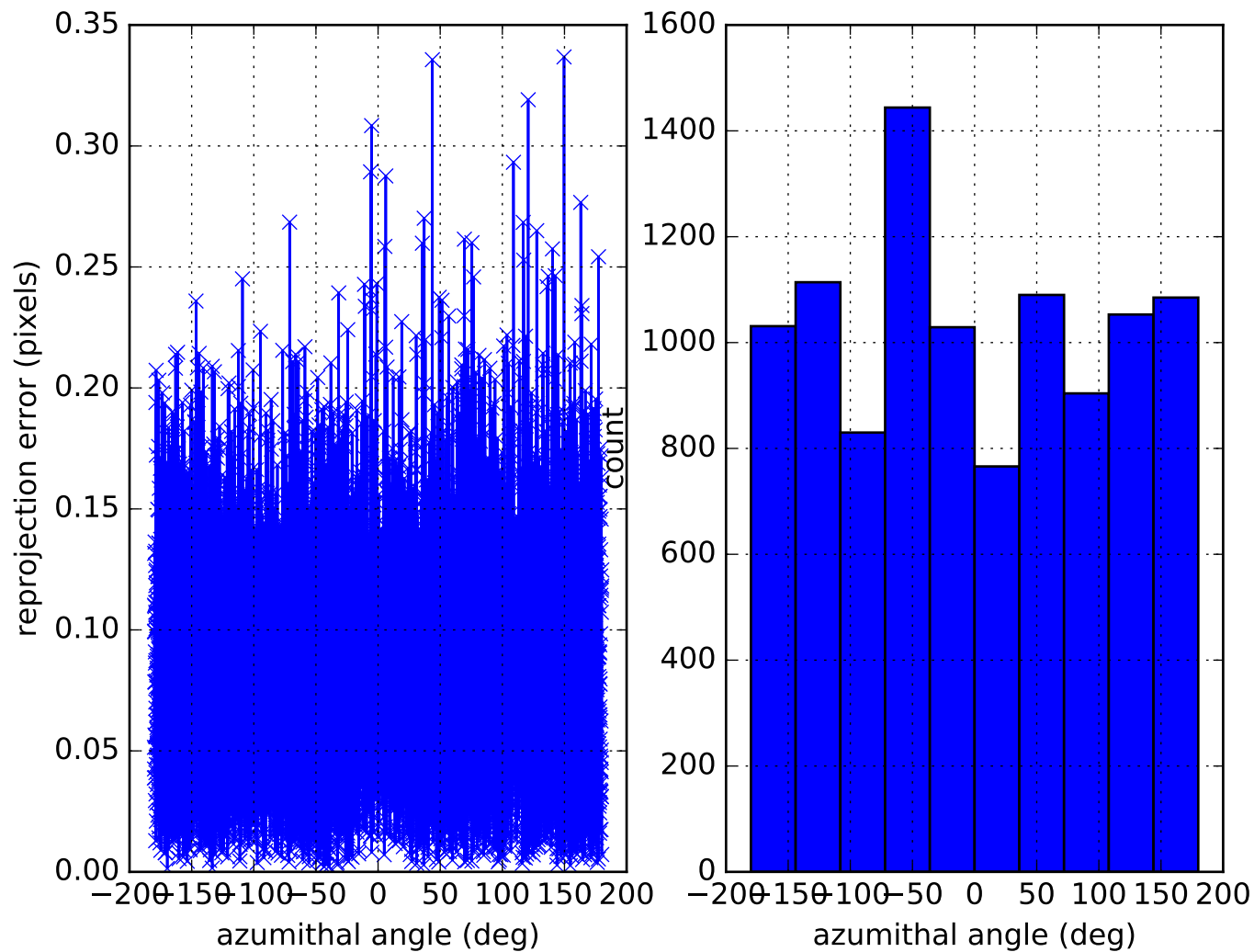
cam0: reprojection errors



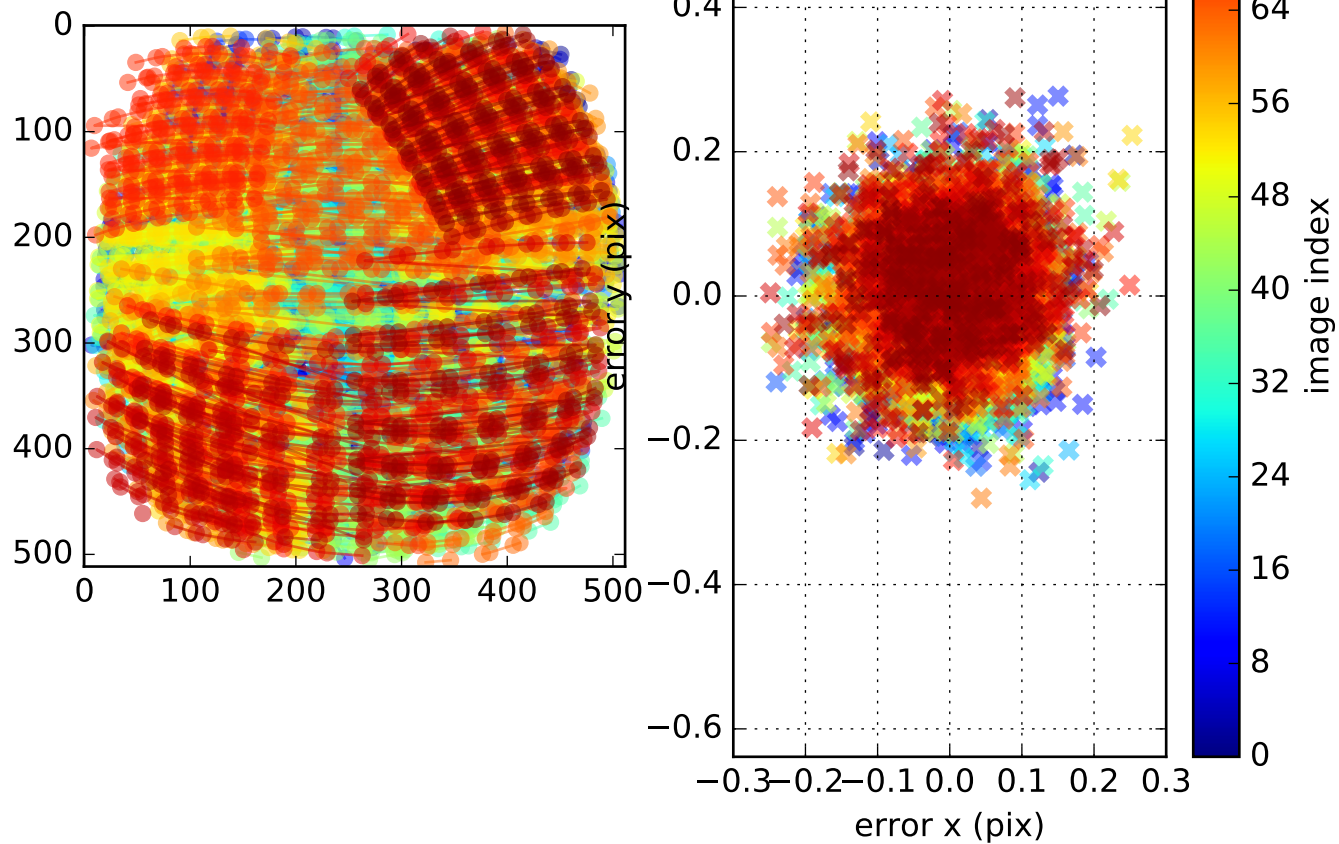
cam1: polar error



cam1: azimuthal error



cam1: reprojection errors





Location of removed outlier corners

