Segmentation with Moment Constraints Gruppenseminar 17.8.12

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Image Segmentation with Moment Constraints



User input



Color only Segmentation



with Moment Constraints

2D Central Moments



2D Central Moments

Area:
$$\mathcal{C}_0 = \left\{ u \in \mathcal{B} \mid c_1 \leq \int_{\Omega} u \, \mathrm{dx} \leq c_2 \right\}$$

Centroid:
$$C_1 = \left\{ u \in \mathcal{B} \mid \mu_1 \leq \frac{\int_{\Omega} x u \, \mathrm{dx}}{\int_{\Omega} u \, \mathrm{dx}} \leq \mu_2 \right\}$$

Covariance:
$$C_2 = \left\{ u \in \mathcal{B} \mid A_1 \leq \frac{\int_{\Omega} (x - \mu)(x - \mu)^\top u \, \mathrm{dx}}{\int_{\Omega} u \, \mathrm{dx}} \leq A_2 \right\}$$

Higher Order Moment Constraints

• The concept can be generalized to moments of arbitrary order.



no constr.

0th order

up to 1st up t

up to 2nd u

up to 3rd up to 6th

up to 6th up to 12th



Input Shape

Segmentation Results









User input



Color only Segmentation



with Moment Constraints

Comparison to Scribble Segmentation



First row: Segmentation with Moment Constraints **Second row:** Segmentation with User Scribbles

Moment Constraints for Tracking



First row: Tracking with Moment Constraints Second row: Histogram based Tracking

3D Area Constraints for Tracking

- Use depth information from Kinect as additional information.
- Compute area in 3D space instead of the image plane.



First row: Area tracking in 2D **Second row:** Area tracking in 3D