# Weekly Exercises 6 

Room: 02.09.023
Wed, 10.06.2015, 14:15-15:45
Submission deadline: Tue, 09.06.2015, 23:59 to windheus@in.tum.de Please send in only Latex-PDF. If you have hand-written solutions, please hand them in during the lecture.

## Laplacian

Exercise 1 (One Point). In this exercise we investigate the eigenvectors of the Laplace matrix $L=M^{-1} C \in \mathbb{R}^{n \times n}$ as introduced in the lecture and last exercise. (In the last exercise the stiffness (or cotangent) matrix $C$ was denoted by $S$.)

1. Show that $\phi$ is an eigenvector of $L$ with eigenvalue $\lambda$ iff it is a solution to the generalized eigenvalue problem

$$
\lambda M \phi=C \phi
$$

2. Show that $\langle\cdot, \cdot\rangle_{M}:=\langle\cdot, M \cdot\rangle$ defines an inner product.
3. Show that the Laplacian matrix $L$ is symmetric with respect to $\langle\cdot, \cdot\rangle_{M}$, i.e. $\langle L x, y\rangle_{M}=\langle x, L y\rangle_{M}$.
4. Show that $L$ has real eigenvalues?
5. Show that you can find eigenvectors $\left\{\phi_{i}\right\}$ of $L$ such that $\Phi^{T} M \Phi=$ Id. Here $\Phi$ is the matrix with the eigenvectors as columns

$$
\Phi=\left(\begin{array}{ccc}
\mid & & \mid \\
\phi_{1} & \ldots & \phi_{n} \\
\mid & & \mid
\end{array}\right) .
$$

6. Let $f \in \mathbb{R}^{n}$, define coefficients $\alpha_{i} \in \mathbb{R}$ by $\alpha_{i}=\left\langle f, \phi_{i}\right\rangle_{M}$. Show that $f=$ $\sum_{i} \alpha_{i} \phi_{i}$, i.e. $\left\{\phi_{i}\right\}$ is an orthonormal basis of $\mathbb{R}^{n}$.

Solution. 1. Let $\phi$ is be an eigenvector of $L$ with eigenvalue $\lambda$, it holds by the definition

$$
\begin{aligned}
\lambda \phi & =L \phi=M^{-1} C \phi \\
\Leftrightarrow \lambda M \phi & =C \phi .
\end{aligned}
$$

2. We need to show that $M$ is positive definite. $M$ is defined by

$$
M_{i, j}= \begin{cases}\frac{A\left(T_{1}\right)+A\left(T_{2}\right)}{12} & \text { if } i \neq j \text { and } T_{1}, T_{2} \text { are common triangles, } \\ \sum_{T \in N(i)} \frac{A(T)}{6} & \text { if } i=j \text { and } N(i) \text { is the set of incident triangles, } \\ 0 & \text { otherwise }\end{cases}
$$

Let $n$ be the number of vertices and $m$ be the number of edges. We now construct matrix $F \in \mathbb{R}^{m \times n}$, such that $M=F^{\top} F$. Let the $e$-th edge connect vertices $i, j$, set $F_{e, i}=F_{e, j}=\sqrt{\frac{A\left(T_{1}\right)+A\left(T_{2}\right)}{12}}$, where $T_{1}, T_{2}$ are the common triangles of vertices $i, j$. Set all other entries of $F$ to zero. Calculating the matrix-matrix product $F^{\top} F$ we get $\left(F^{\top} F\right)_{i, j}=\sum_{e} F_{e, i} F_{e, j}$. Thus $\left(F^{\top} F\right)_{i, j}=$ $\frac{A\left(T_{1}\right)+A\left(T_{2}\right)}{12}$ if $i, j$ are adjacent and $\left(F^{\top} F\right)_{i, j}=0$ otherwise. If $i=j$ we get $\left(F^{\top} F\right)_{i, j}=\sum_{e} F_{e, i}^{2}=\sum_{T \in N(i)} \frac{A(T)}{6}$. Thus $M=F^{\top} F$ and $m$ positive semidefinite. Since $M$ is invertible, $M$ is also positive definite.
3. Recall that $\langle A x, y\rangle=\left\langle x, A^{*} y\right\rangle$ and for some scalar $\lambda \in \mathbb{C}$ it holds $\lambda\langle x, y\rangle=$ $\langle x, \bar{\lambda} y\rangle$. Since $M, C$ are real and symmetric, we have $\langle L x, y\rangle_{M}=\langle M L x, y\rangle=$ $\langle C x, y\rangle=\langle x, C y\rangle=\langle x, M L y\rangle=\langle x, L y\rangle_{M}$. Now let $\lambda \phi=L \phi$, we have $\lambda\langle\phi, \phi\rangle_{M}=\langle\lambda \phi, \phi\rangle_{M}=\langle L \phi, \phi\rangle_{M}=\langle\phi, L \phi\rangle_{M}=\langle\phi, \lambda \phi\rangle_{M}=\bar{\lambda}\langle\phi, \phi\rangle_{M}$. Since $\langle\phi, \phi\rangle_{M}>0$ it holds $\lambda=\bar{\lambda}$.
4. Let $L \phi_{1}=\lambda_{1} \phi_{1}, L \phi_{2}=\lambda_{2} \phi_{2},\left\|\phi_{1}\right\|_{M}=\left\|\phi_{2}\right\|_{M}=1$. We get $\lambda_{1}\left\langle\phi_{1}, \phi_{2}\right\rangle_{M}=$ $\left\langle\lambda_{1} \phi_{1}, \phi_{2}\right\rangle_{M}=\left\langle L \phi_{1}, \phi_{2}\right\rangle_{M}=\left\langle\phi_{1}, L \phi_{2}\right\rangle_{M}=\left\langle\phi_{1}, \lambda_{2} \phi_{2}\right\rangle_{M}=\lambda_{2}\left\langle\phi_{1}, \phi_{2}\right\rangle_{M}$. Thus $\left\langle\phi_{1}, \phi_{2}\right\rangle_{M}=0$, if $\lambda_{1} \neq \lambda_{2}$ and $\left\langle\phi_{1}, \phi_{2}\right\rangle_{M}=1$, if $\lambda_{1}=\lambda_{2}$ (ignoring eigenvalues of multiplicity $>1$ ).
5. $\alpha_{i}=\left\langle f, \phi_{i}\right\rangle_{M}=\left\langle\phi_{i}, M f\right\rangle$, thus $\alpha=\Phi^{\top} M f=\Phi^{-1} f$, thus $f=\Phi \alpha$.

## The Heat Equation

Let $u: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^{n}$ be a continuous sequence of vectors $u(t) \in \mathbb{R}^{n}$, where we call $t$ the time parameter. Since the eigenvectors $\left\{\phi_{i}\right\}$ of $L$ form an orthonormal basis of $\mathbb{R}^{n}, u(t)$ can be written as $u(t)=\sum_{i} \alpha_{i}(t) \phi_{i}$, where the coefficients $\alpha_{i}: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$ are real-valued functions of time parameter $t$. We say $u(t)$ is a discrete distribution of heat if it satisfies the heat equation

$$
\frac{\partial}{\partial t} u(t)=L u(t)
$$

From the linearity of differentiation we can write $\frac{\partial}{\partial t} u(t)$ as

$$
\frac{\partial}{\partial t} u(t)=\sum_{i} \phi_{i} \frac{\partial}{\partial t} \alpha_{i}(t)
$$

Exercise 2 (One Point). Let $u: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^{n}, u(t)=\sum_{i} \alpha_{i}(t) \phi_{i}$, now be any such sequence of vectors that satisfies the heat equation.

1. Show that there exists coefficients $c_{i} \in \mathbb{R}, 1 \leq i \leq n$, such that

$$
\alpha_{i}(t)=c_{i} \exp \left(\lambda_{i} t\right)
$$

2. Let $u_{0} \in \mathbb{R}^{n}$ and set $u(0)=u_{0}$. Show that the coefficients $c_{i}$ can be computed by $c_{i}=\left\langle u_{0}, \phi_{i}\right\rangle_{M}$.

The exercise shows that if we let some initial heat distribution $u_{0}$ diffuse over time $t$ the resulting heat distribution $u(t)$ can be computed by

$$
u(t)=\sum_{i}\left\langle u_{0}, \phi_{i}\right\rangle_{M} \exp \left(\lambda_{i} t\right) \phi_{i} .
$$

If our triangle mesh has $n$ vertices we can define the heat kernel signature $\operatorname{HKS}\left(v_{i}, t\right)$ for $v_{i}$ at time $t$ by

$$
\operatorname{HKS}\left(v_{i}, t\right)=\sum_{i}\left\langle e_{i}, \phi_{i}\right\rangle_{M} \exp \left(\lambda_{i} t\right) \phi_{i},
$$

where $e_{i} \in \mathbb{R}^{n}$ is the vector that is 0 everywhere except in the $i$-th component. Now we can discretize the time line by taking a finite subset $\mathcal{T}=\left\{t_{1}, \ldots, t_{T}\right\} \subset \mathbb{R}_{\geq 0}$ and define the vector valued heat kernel signature of vertex $v_{i}$ by

$$
\operatorname{HKS}_{\mathcal{T}}\left(v_{i}\right)=\left(\operatorname{HKS}\left(v_{i}, t_{1}\right), \ldots, \operatorname{HKS}\left(v_{i}, t_{T}\right)\right)
$$

Solution. 1. Let $u(t)=\sum_{i} \alpha_{i}(t) \phi_{i}$, we expand the heat equation on both sides:

$$
\begin{aligned}
\frac{\partial}{\partial t} u(t) & =L u(t) \\
\sum_{i} \phi_{i} \frac{\partial}{\partial t} \alpha_{i}(t) & =L\left(\sum_{i} \alpha_{i}(t) \phi_{i}\right)=\sum_{i} \alpha_{i}(t) L \phi_{i} \\
\sum_{i} \phi_{i} \frac{\partial}{\partial t} \alpha_{i}(t) & =\sum_{i} \phi_{i} \lambda_{i} \alpha_{i}(t)
\end{aligned}
$$

Since vectors $\phi_{i}$ are linear independent, it holds for all $i$ :

$$
\frac{\partial}{\partial t} \alpha_{i}(t)=\lambda_{i} \alpha_{i}(t)
$$

From basic analysis we know that $\alpha_{i}(t)=c_{i} \exp \left(\lambda_{i} t\right)$, where $c_{i} \in \mathbb{R}$ is any number, is a solution to this differential equation.
2. Since $\left\{\phi_{i}\right\}$ is an orthonormal basis of $\mathbb{R}^{n}$ it holds $u_{0}=\sum_{i}\left\langle\phi_{i}, u_{0}\right\rangle_{M} \phi_{i}$. Thus $\left\langle\phi_{i}, u_{0}\right\rangle_{M}=\alpha_{i}(0)=c_{i} \exp \left(\lambda_{i} 0\right)=c_{i}$.

## Programming: The Discrete Laplace Operator

Exercise 3 (Two points). Download and expand the file exercise6.zip from the lecture website. Modifiy the files cotanmatrix.m, massmatrix.m, heatsimulation.m, and hks.m to implement the functions as explained below. You can run the script exercise.m to test and visualize your solution.
cotanmatrix.m The function should compute the matrix $C \in \mathbb{R}^{n \times n}$ based on the cotangent scheme as defined in the lecture. The triangle mesh is given by matrices $V \in \mathbb{R}^{n \times 3}$ and $F \in \mathbb{N}^{m \times 3}$, where $n$ is the number of vertices and $m$ the number of triangles. $C$ should be returned in sparse format.
massmatrix.m The function should compute the matrix $M \in \mathbb{R}^{n \times n}$ based on the scheme defined in the lecture. The triangle mesh is given by matrices $V \in \mathbb{R}^{n \times 3}$ and $F \in \mathbb{N}^{m \times 3}$, where $n$ is the number of vertices and $m$ the number of triangles. $M$ should be returned in sparse format.
exercise.m Look at the code for the eigen decomposition. You see it is very easy to compute the generalized eigen decomposition $\lambda M \phi=C \phi$ by the matlab function eigs.
heatsimulation.m Given some initial heat distribution $u_{0} \in \mathbb{R}^{n}$, the function simulates the diffusion of heat on the mesh. The function should display the distribution of heat at several given time points $t_{1}, \ldots, t_{T} \in \mathbb{R}_{+}$.
hks.m The function should compute for each point on the mesh the heat kernel signature at time points $t_{1}, \ldots, t_{T} \in \mathbb{R}_{+}$.

