

Reminder: Fast optimization challenge

- ▶ Minimize the inpainting energy

$$E(u) = \frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \sum_{i=1}^{2N} h_\varepsilon((Du)_i) + \beta \|u\|^2$$

- ▶ Huber penalty $h_\varepsilon(x) = \begin{cases} \frac{x^2}{2\varepsilon} & \text{if } |x| \leq \varepsilon, \\ |x| - \frac{\varepsilon}{2} & \text{otherwise.} \end{cases}$

- ▶ Given all the parameters, return the solution once

$$\frac{E(u^k) - E(u^*)}{E(u^*)} < \delta$$

- ▶ See template `challenge_hubert_inpainting.m`

Gradient descent

$$E(u) = \frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \sum_{i=1}^{2N} h_\varepsilon((Du)_i) + \beta \|u\|^2$$

Update

$$u^{k+1} = u^k - \tau^k \nabla E(u^k)$$

(P-GD)

with a suitable step size:

- ▶ Line search:

$$\tau_k \leftarrow \text{large number}$$

$$\text{while } E(u^k - \tau_k \nabla E(u^k)) > E(u^k) - \alpha \tau_k \|\nabla E(u^k)\|^2$$

$$\tau_k \leftarrow \beta \tau_k$$

end

- ▶ Compute Lipschitz constant of ∇E (see exercise).

Primal proximal gradient

$$E(u) = \underbrace{\frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2}_{=:G(u)} + \underbrace{\sum_{i=1}^{2N} h_\varepsilon((Du)_i)}_{=:R(u)}$$

Update:

$$\begin{aligned} u^{k+1/2} &= u^k - \tau^k \nabla R(u^k) \\ u^{k+1} &= \text{prox}_{\tau^k, G}(u^{k+1/2}) \\ &= \underset{u}{\operatorname{argmin}} \frac{1}{2} \|u - u^{k+1/2}\|^2 + \tau^k G(u) \end{aligned} \tag{P-PG}$$

- ▶ What are the formulas for ∇R and $\text{prox}_{\tau^k, G}(u^{k+1/2})$?
- ▶ What is the Lipschitz-constant of ∇R ?

Dual formulation

Let us compute a dual formulation for

$$E(u) = \underbrace{\frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2}_{=:G(u)} + \underbrace{\sum_{i=1}^{2N} h_\varepsilon((Du)_i)}_{=:F(Du)}$$

We know from Fenchel's duality theorem

$$\min_u G(u) + F(Du) = \max_q -G^*(-D^*q) - F^*(q).$$

Let \hat{u} be a solution of the primal problem and let \hat{q} be a solution of the dual problem, then

$$D^*\hat{q} \in \partial G(\hat{u}), \quad \hat{q} \in \partial F(D\hat{u})!$$

Dual formulation

To actually compute the dual note that

$$\begin{aligned} G(u) &= \frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2 \\ &= \frac{1}{2} \langle u, (\lambda m^T m + 2\beta I)u \rangle - \langle u, \lambda m^T m f \rangle + (\text{stuff indep. of } u) \end{aligned}$$

The matrix $(\lambda m^T m + 2\beta I)$ is symmetric and positive definite, even diagonal, and by taking the element-wise square root we find a matrix C such that $CC = \lambda m^T m + 2\beta I$. Thus

$$\begin{aligned} G(u) &= \frac{1}{2} \langle u, CCu \rangle - \langle Cu, \lambda C^{-1} m^T m f \rangle + (\text{stuff indep. of } u) \\ &= \frac{1}{2} \|Cu - \underbrace{\lambda C^{-1} m^T m f}_{=: b}\|^2 + (\text{stuff indep. of } u) \end{aligned}$$

Dual formulation

Up to neglectable constants we have

$$G(u) = \frac{1}{2} \|Cu - b\|^2$$

As a conclusion from chapter 2 "Conjugate of image functions" (or by substitution) we find

$$\begin{aligned} G^*(p) &= \left(\frac{1}{2} \|\cdot - b\|^2 \circ C \right)^*(p) \\ &= \left(\frac{1}{2} \|\cdot - b\|^2 \right)^*(C^{-1}p) \\ &= \left(\frac{1}{2} \|\cdot\|^2 + \langle \cdot, b \rangle \right)(C^{-1}p) \\ &= \frac{1}{2} \|C^{-1}p + b\|^2 + (\text{stuff indep. of } p) \end{aligned}$$

Dual formulation

Now consider

$$F(Du) = \sum_{i=1}^{2N} h_\varepsilon((Du)_i)$$

and compute $F^*(p)$. Note that it is sufficient to find the conjugate of

$$h_\varepsilon(x) = \begin{cases} \frac{x^2}{2\varepsilon} & \text{if } |x| \leq \varepsilon, \\ |x| - \frac{\varepsilon}{2} & \text{otherwise.} \end{cases}$$

and a short calculation shows

$$F^*(q) = \sum_{i=1}^{2N} \left(\frac{\epsilon}{2} q_i^2 + \iota_{|\cdot| \leq 1}(q_i) \right).$$

Dual formulation

Dual formulation:

$$\hat{q} = \operatorname{argmin}_q G^*(-D^*q) + F^*(q)$$

with

$$G^*(p) = \frac{1}{2} \|C^{-1}p + b\|^2,$$

$$F^*(q) = \sum_{i=1}^{2N} \left(\frac{\epsilon}{2} q_i^2 + \iota_{|\cdot| \leq 1}(q_i) \right),$$

$$C = \sqrt{\lambda m^T m + 2\beta I},$$

$$b = \lambda C^{-1} m^T m f,$$

and since $D^*\hat{q} \in \partial G(\hat{u}) = \{C(C\hat{u} - b)\}$ for \hat{u} being the primal solution we find

$$\hat{u} = (CC)^{-1}(D^*\hat{q} + Cb).$$

Gradient projection on the dual

Dual energy written in a compact form:

$$\min_q \frac{1}{2} \|C^{-1}D^*q - b\|^2 + \frac{\epsilon}{2}\|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q)$$

Updates for gradient projection

$$q^{k+1} = \text{proj}_{\|\cdot\|_\infty \leq 1} (q^k - \tau^k DC^{-1}(C^{-1}D^*q^k - b) - \tau^k \epsilon q^k)$$

(D-GP)

Updates for proximal gradient

$$q^{k+1/2} = q^k - \tau^k DC^{-1}(C^{-1}D^*q^k - b)$$

$$q^{k+1} = \text{prox}_{\frac{\epsilon}{2}\|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q)}(q^{k+1/2})$$

(D-PG)

Stepsize restrictions? Line search?

Saddle point form

Primal:

$$\min_u \underbrace{\frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2}_{=:G(u)} + \underbrace{\sum_{i=1}^{2N} h_\varepsilon((Du)_i)}_{=:F(Du)}$$

Dual:

$$\min_q \frac{1}{2} \|C^{-1}D^*q - b\|^2 + \frac{\epsilon}{2} \|q\|^2 + \iota_{|\cdot|_\infty \leq 1}(q)$$

Saddle-point / primal-dual:

$$\begin{aligned} & \min_u \max_q G(u) + \langle Du, q \rangle - F^*(q) \\ &= \min_u \max_q \frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2 + \langle Du, q \rangle \\ & \quad - \frac{\epsilon}{2} \|q\|^2 - \iota_{|\cdot|_\infty \leq 1}(q) \end{aligned}$$

Primal PDHG

Saddle-point / primal-dual:

$$\begin{aligned} & \min_u \max_q G(u) + \langle Du, q \rangle - F^*(q) \\ &= \min_u \max_q \frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2 + \langle Du, q \rangle \\ & \quad - \frac{\epsilon}{2} \|q\|^2 - \iota_{\| \cdot \|_\infty \leq 1}(q) \end{aligned}$$

Primal-dual hybrid gradient method:

$$\begin{aligned} q^{k+1} &= \text{prox}_{\sigma F^*}(q^k + \sigma D \bar{u}^k), \\ u^{k+1} &= \text{prox}_{\tau G}(u^k - \tau D^* q^{k+1}), \\ \bar{u}^{k+1} &= u^{k+1} + (u^{k+1} - u^k). \end{aligned} \tag{P-PDHG}$$

Prox operators? Stepsize restriction? Algorithm with adaptive stepsizes for strongly convex problems?

Saddle point form

Primal:

$$\min_u \underbrace{\frac{\lambda}{2} \|m \cdot (u - f)\|^2 + \beta \|u\|^2}_{=:G(u)} + \underbrace{\sum_{i=1}^{2N} h_\varepsilon((Du)_i)}_{=:F(Du)}$$

Dual:

$$\min_q \frac{1}{2} \|C^{-1}D^*q - b\|^2 + \frac{\epsilon}{2} \|q\|^2 + \iota_{|\cdot|_\infty \leq 1}(q)$$

Saddle-point / dual-primal:

$$\min_q \max_v \langle v, C^{-1}D^*q - b \rangle - \frac{1}{2} \|v\|^2 + \frac{\epsilon}{2} \|q\|^2 + \iota_{|\cdot|_\infty \leq 1}(q)$$

Primal PDHG

Saddle-point / dual-primal:

$$\min_q \max_v \langle v, C^{-1}D^*q - b \rangle - \frac{1}{2}\|v\|^2 + \frac{\epsilon}{2}\|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q)$$

Primal-dual hybrid gradient method:

$$\begin{aligned} v^{k+1} &= \text{prox}_{\frac{\sigma}{2}\|\cdot\|^2 + \sigma\langle \cdot, b \rangle}(q^k + \sigma C^{-1}D^*\bar{q}^k), \\ q^{k+1} &= \text{prox}_{\tau F^*}(q^k - \tau D C^{-1}v^{k+1}), \\ \bar{q}^{k+1} &= q^{k+1} + (q^{k+1} - q^k). \end{aligned} \tag{D-PDHG}$$

Prox operators? Stepsize restriction? Algorithm with adaptive stepsizes for strongly convex problems?

Splitting methods / ADMM

$$\min_u G(u) + F(Du)$$

Introduce a new variable d and the constraint $Du = d$:

$$\min_{u,d} G(u) + F(d) \quad \text{s.t. } Du = d$$

Formulate constraint in primal-dual form

$$\min_{u,d} \max_p G(u) + F(d) + \langle Du - d, p \rangle.$$

You could apply PDHG now:

$$p^{k+1} = p^k + \sigma(D\bar{u}^k - \bar{d}^k)$$

$$(u^{k+1}, d^{k+1}) = (\text{prox}_{\tau G}(u^k - \tau D^* p^{k+1}), \text{prox}_{\tau F}(d^k + \tau p^{k+1}))$$

$$(\bar{u}^{k+1}, \bar{d}^{k+1}) = (u^{k+1}, d^{k+1}) + ((u^{k+1}, d^{k+1}) - (u^k, d^k)),$$

(P-GP-PDHG)

Splitting methods / ADMM

$$\min_{u,d} \max_p G(u) + F(d) + \langle Du - d, p \rangle.$$

Alternatively, augment the above term by defining

$$L(u, d, p) = G(u) + F(d) + \langle Du - d, p \rangle + \frac{\lambda}{2} \|Du - d\|^2$$

and apply ADMM

$$\begin{aligned} u^{k+1} &= \underset{u}{\operatorname{argmin}} L(u, d^k, p^k), \\ d^{k+1} &= \underset{d}{\operatorname{argmin}} L(u^{k+1}, d, p^k), \\ p^{k+1} &= p^k + \lambda(Du^{k+1} - d^{k+1}). \end{aligned} \tag{P-ADMM}$$

Update equations? How do we solve the linear system arising in the u -update? Nice: Unconditionally stable independent of λ , but convergence speed depends on it!

Splitting methods / ADMM

Consider the dual problem

$$\min_q \frac{1}{2} \|C^{-1}D^*q - b\|^2 + \frac{\epsilon}{2} \|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q)$$

Introduce a new variable z along with the constraint $z = q$ and formulate constraint in primal-dual form

$$\min_{q,z} \max_v \frac{1}{2} \|C^{-1}D^*z - b\|^2 + \frac{\epsilon}{2} \|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q) + \langle z - q, v \rangle.$$

You could apply PDHG now!

$$v^{k+1} = v^k + \sigma(\bar{z}^k - \bar{q}^k)$$

$$z^{k+1} = \text{prox}_{\frac{\tau}{2}\|C^{-1}D^* - b\|^2}(z^k - \tau v^{k+1})$$

$$q^{k+1} = \text{prox}_{\tau \frac{\epsilon}{2}\|\cdot\|^2 + \iota_{\|\cdot\|_\infty \leq 1}}(d^k + \tau v^{k+1})$$

$$(\bar{z}^{k+1}, \bar{q}^{k+1}) = 2(z^{k+1}, q^{k+1}) - (z^k, q^k),$$

(D-GP-PDHG)

Splitting methods / ADMM

$$\min_{q,z} \max_v \frac{1}{2} \|C^{-1}D^*z - b\|^2 + \frac{\epsilon}{2}\|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q) + \langle z - q, v \rangle.$$

Alternatively, augment the above term by defining

$$\begin{aligned} L(q, z, v) = & \frac{1}{2} \|C^{-1}D^*z - b\|^2 + \frac{\epsilon}{2}\|q\|^2 + \iota_{\|\cdot\|_\infty \leq 1}(q) \\ & + \langle z - q, v \rangle + \frac{\lambda}{2}\|z - q\|^2 \end{aligned}$$

and apply ADMM

$$\begin{aligned} q^{k+1} &= \underset{q}{\operatorname{argmin}} L(q, z^k, v^k), \\ z^{k+1} &= \underset{z}{\operatorname{argmin}} L(q^{k+1}, z, v^k), \\ v^{k+1} &= v^k + \lambda(q^{k+1} - z^{k+1}). \end{aligned} \tag{D-ADMM}$$

Update equations? What is a good λ ? We called this ADMM, do you know a different name (since $K = I$)?

Possible algorithm:

We have discussed

1. Primal gradient descent → (P-GD)
2. Primal proximal gradient → (P-PG)
3. Dual gradient projection → (D-GP)
4. Dual proximal gradient → (D-PG)
5. PDHG on primal problem → (P-PDHG)
6. PDHG on dual problem → (D-PDHG)
7. Primal graph-projection PDHG → (P-GP-PDHG)
8. Dual graph-projection PDHG → (D-GP-PDHG)
9. Primal ADMM → (P-ADMM)
10. Dual ADMM → (D-ADMM)

Choose your weapon and start coding!!