



Chapter 3

Duality

Convex Optimization for Computer Vision
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Duality

Motivation

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Duality



Summary: descent methods

For energies of the form

$$u^* \in \arg \min_{u \in \mathbb{R}^n} E(u),$$

for $E : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ proper, closed, convex, we discussed

Gradient descent:

- $\text{dom } E = \mathbb{R}^n$
- For $E \in \mathcal{F}_L^{1,1}(\mathbb{R}^n)$ energy convergence in $\mathcal{O}(1/k)$
- For $E \in \mathcal{S}_{m,L}^{1,1}(\mathbb{R}^n)$ energy and iterate convergence in $\mathcal{O}(c^k)$

Subgradient descent:

- $\text{dom}(E) = \mathbb{R}^n$
- Applicable to any Lipschitz-continuous convex energy
- Usually rather slow

Gradient projection: Generalizes gradient descent to arbitrary (nonempty, closed, convex) $\text{dom}(E)$.



How powerful is the gradient projection algorithm?

Consider the total variation denoising problem

$$u^* \in \operatorname{argmin}_u \frac{1}{2} \|u - f\|_2^2 + \alpha \|Du\|_{2,1},$$

with the finite difference operator $D : \mathbb{R}^{n \times m \times c} \rightarrow \mathbb{R}^{nm \times 2c}$.

Is subgradient descent really the best we can do despite the “nice” strongly convex energy?

Let's try something crazy to try to find a better algorithm:

$$\|g\| = \max_{|q| \leq 1} \langle q, g \rangle$$



Following the crazy idea...

The previous simple observation tells us that

$$\begin{aligned}
 \|g\|_{2,1} &= \sum_i \|g_i\| = \sum_i \max_{|q_i| \leq 1} \langle q_i, g_i \rangle \\
 &= \max_{|q_i| \leq 1} \underbrace{\sum_i \langle q_i, g_i \rangle}_{=: \langle g, q \rangle} \\
 &= \max_{\max_i \|q_i\| \leq 1} \langle g, q \rangle = \max_{\|q\|_{2,\infty} \leq 1} \langle g, q \rangle
 \end{aligned}$$

We may write

$$\begin{aligned}
 \min_u \frac{1}{2} \|u - f\|_2^2 + \alpha \|Du\|_1 &= \min_u \frac{1}{2} \|u - f\|_2^2 + \alpha \max_{\|q\|_{2,\infty} \leq 1} \langle Du, q \rangle \\
 &= \min_u \max_{\|q\|_{2,\infty} \leq 1} \frac{1}{2} \|u - f\|_2^2 + \alpha \langle Du, q \rangle
 \end{aligned}$$

Can we switch min and max?



TV Minimization

Saddle point problems¹

Let C and D be non-empty closed convex sets in \mathbb{R}^n and \mathbb{R}^m , respectively, and let S be a continuous finite concave-convex function on $C \times D$. If either C or D is bounded, one has

$$\inf_{v \in D} \sup_{q \in C} S(v, q) = \sup_{q \in C} \inf_{v \in D} S(v, q).$$

We can therefore compute

$$\begin{aligned} \min_u \frac{1}{2} \|u - f\|_2^2 + \alpha \|Du\|_1 &= \min_u \max_{\|q\|_{2,\infty} \leq 1} \frac{1}{2} \|u - f\|_2^2 + \alpha \langle Du, q \rangle \\ &= \max_{\|q\|_{2,\infty} \leq 1} \min_u \frac{1}{2} \|u - f\|_2^2 + \alpha \langle Du, q \rangle \end{aligned}$$

¹Rockafellar, Convex Analysis, Corollary 37.3.2



TV Minimization

Now the inner minimization problem obtains its optimum at

$$\begin{aligned} 0 &= u - f + \alpha D^* q, \\ \Rightarrow u &= f - \alpha D^* q. \end{aligned}$$

The remaining problem in q becomes

$$\begin{aligned} &\max_{\|q\|_{2,\infty} \leq 1} \frac{1}{2} \|f - \alpha D^* q - f\|_2^2 + \alpha \langle D(f - \alpha D^* q), q \rangle \\ &= \max_{\|q\|_{2,\infty} \leq 1} \frac{1}{2} \|\alpha D^* q\|_2^2 + \alpha \langle Df, q \rangle - \|\alpha D^* q\|_2^2 \\ &= \max_{\|q\|_{2,\infty} \leq 1} -\frac{1}{2} \|\alpha D^* q - f\|_2^2 \end{aligned}$$



TV Minimization

Since we prefer minimizations over maximizations, we write

$$\begin{aligned}\hat{q} &= \underset{\|q\|_{2,\infty} \leq 1}{\operatorname{argmax}} -\frac{1}{2} \|\alpha D^* q - f\|_2^2 \\ &= \underset{\|q\|_{2,\infty} \leq 1}{\operatorname{argmin}} \frac{1}{2} \left\| D^* q - \frac{f}{\alpha} \right\|_2^2\end{aligned}$$

This is a problem we know how to solve! An L -smooth function over a simple convex set: Gradient projection

$$q^{k+1} = \pi_C \left(q^k - \tau D \left(D^* q^k - \frac{f}{\alpha} \right) \right),$$

where $C = \{q \in \mathbb{R}^{nm \times 2c} \mid \|q\|_{2,\infty} \leq 1\}$.



A conceptual way to reformulate energy minimization problems?

Maybe our idea

$$\|g\| = \max_{|q| \leq 1} \langle q, g \rangle$$

was not so crazy but rather conceptual?

Definition: Convex Conjugate

We define the *convex conjugate* of the function

$E : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ to be

$$E^*(p) = \sup_{u \in \mathbb{R}^n} (\langle u, p \rangle - E(u)).$$

Convexity of the Convex Conjugate

The convex conjugate E^* of any proper function $E : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ is convex.



Proof: Board

Convexity of the Convex Conjugate

The convex conjugate E^* of any proper function $E : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ is closed.

Proof: Linear functions are closed and arbitrary intersections of closed sets are closed.