Convex Optimization for Computer Vision Lecture: M. Möller and T. Möllenhoff Exercises: E. Laude Summer Semester 2016

Weekly Exercises 10

Room 01.09.014 Friday, 8.7.2016, 09:00-11:00 Submission deadline: Wednesday, 6.7.2016, 14:15, Room: 02.09.023

Theory

Exercise 1 (4 points). The Huber penalty $h_{\varepsilon} : \mathbb{R} \to \mathbb{R}$ is given as

$$h_{\varepsilon}(x) = \begin{cases} \frac{x^2}{2\varepsilon} & \text{if } |x| \le \varepsilon, \\ |x| - \frac{\varepsilon}{2} & \text{otherwise.} \end{cases}$$

1. Show that the huber penalty can be expressed as the infimal convolution of the functions $f: \mathbb{R} \to \mathbb{R}$ with $f(x) := \frac{x^2}{2\varepsilon}$ and $g: \mathbb{R} \to \mathbb{R}$ with g(x) := |x|:

 $h_{\varepsilon}(x) = (f \Box q)(x).$

 $t(x) := \sum_{i=1}^{2N} h_{\varepsilon}(x_i).$

2. Compute the convex conjugate of the function
$$t : \mathbb{R}^{2N} \to \mathbb{R}$$
 defined as

2. Compute the convex conjugate of the function
$$t: \mathbb{R}^{-1} \to \mathbb{R}$$
 defined

Exercise 2 (12 Points). Complete the optimization challange. Only reasonable attempts will be counted.

Computer Vision Group

Technische Universität München

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(12 Points)

(4 Points)