Analysis of Three-Dimensional Shapes F. R. Schmidt, M. Vestner, Z. Lähner Summer Semester 2016

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Weekly Exercises 2

Room: 02.09.023 Wed, 04.05.2016, 14:00-16:00

Submission deadline: Tue, 03.05.2016, 23:59 to laehner@in.tum.de

Mathematics: Tangent spaces and Curvature

Exercise 1 (2 points). 1. Consider the following two coordinate maps of the sphere in \mathbb{R}^3 .

$$x_{1}: \{(x,y) \in \mathbb{R}^{2} \mid x^{2} + y^{2} < 1\} \to \mathbb{R}^{3}$$

$$(u,v) \mapsto (u,v,\sqrt{1-u^{2}-v^{2}})$$

$$x_{2}:] -10,10[\times] -10,10[\to \mathbb{R}^{3}$$

$$(u,v) \mapsto \frac{1}{u^{2}+v^{2}+1}(2u,2v,u^{2}+v^{2}-1)$$
(2)

Calculate two vectors in \mathbb{R}^3 spanning the tangent space at p = (2/3, 2/3, 1/3). Which vectors a, b in the domain of Dx_1, Dx_2 are mapped to the tangent vectors you gave before?

2. Proof that the tangent space $T_pM \subset \mathbb{R}^n$ of a submanifold $M \subset \mathbb{R}^n$ of dimension $m \leq n$ is a linear subspace and does not depend on the choice of the choosen coordinate map (x_i, U_i) . (Lemma 3 from the Manifold chapter)

Exercise 2 (1 point). Find a coordinate map $\mathbf{x}: \mathbb{R}^2 \to \mathbb{R}^3$ of the torus

$$T = \left\{ (x, y, z) \in \mathbb{R}^3 | \left(\sqrt{x^2 + y^2} - a \right)^2 + z^2 = r^2 \right\}$$

with a > r > 0. (It can of course not cover the complete manifold.)

Exercise 3 (1 point). The circle with radius r can be represented by the implicit formulation

$$\varphi : \mathbb{R}^2 \to \mathbb{R}$$
$$x \mapsto \sqrt{\langle x, x \rangle}$$
$$C_r = \varphi^{-1}(r)$$

Calculate the curvature on each point of C_r .

Exercise 4 (2 points). Show that the push-forward is a linear mapping.

Programming: Curvature

Download the supplementary material from the homepage. It contains some blackwhite silhouette images from the MPEG7 dataset

(http://www.dabi.temple.edu/~shape/MPEG7/dataset.html) and a file to extract contour information from these images.

Exercise 5 (2 points). Read out the image files bat-9.gif, device7-1.gif, turtle-1.gif into matrices (use imread, it reads positive integers. Changing the type to double will help). Include an image for each sub-exercise in your solution sheet.

- 1. Calculate the curvature on the contour. It can be seen as the level set function somewhere between 0 and 1 so the formula $\kappa(p) = \operatorname{div}\left(\frac{\nabla F(\cdot)}{||\nabla F(\cdot)||}\right)(p)$ from the lecture can be used. There are imgradient and imgradientxy in Matlab or implement your own finite element gradient as an exercise (it's quite easy). The divergence can be calculated with divergence.
- 2. The result from the last exercise was pretty ugly. The reason is that the function we considered was not smooth but went zig-zag along the edges of the pixels. Use a gaussian filter on the image before calculating the curvature. (See imgaussfilt) Use the extract_contour.m from the supplementary material to get a binary mask for the contour with different thickness. Play around with different σ for the filter and thicknesses of the mask.

Exercise 6 (1 point). In most applications we want to find out which shapes are similar to each other. Create a descriptor for each shape in the supplementary material and create a histogram of the different curvatures on the contour (don't forget to normalize because normally the contours will not have the same amount of points). There is a Matlab function histogram if you are not familiar with histograms.

Compare the descriptor of device7-1 to all other descriptors (for example with the Euclidean distance) and sort the remaining shapes in order of similarity to device7-1.