

# Chapter 1

## Convex Analysis

*Convex Optimization for Machine Learning & Computer Vision*  
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Convex Analysis

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Convex Set

Convex Function

Existence of Minimizer

Subdifferential

Convex Conjugate

Duality Theory

Proximal Operator



# Convex Set



## Assume

- $\mathbb{E}$  is a Euclidean space (finite dimensional vector space), equipped with the inner product  $\langle \cdot, \cdot \rangle$ , e.g.  $\langle u, v \rangle = u \cdot v$ .
- $C$  is a closed convex subset in  $\mathbb{E}$ .
- $J$  is a convex objective function.

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## Convex optimization

$$\text{minimize } J(u) \quad \text{over } u \in C.$$

First questions:

- What is a convex set?
- What is a convex function?

# Convex set

## Definition

A set  $C$  is said to be **convex** if

$$\alpha u + (1 - \alpha)v \in C, \quad \forall u, v \in C, \quad \forall \alpha \in [0, 1].$$



## Convex Set

Convex Function

Existence of Minimizer

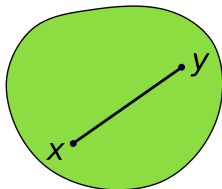
Subdifferential

Convex Conjugate

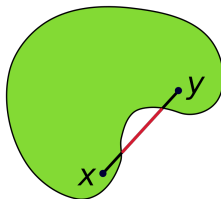
Duality Theory

Proximal Operator

convex



non-convex



## Definition

- A set  $C \subset \mathbb{E}$  is **open** if  $\forall u \in C, \exists \epsilon > 0$  s.t.  $B_\epsilon(u) \subset C$ , where  $B_\epsilon(u) := \{v \in \mathbb{E} : \|v - u\| < \epsilon\}$ .
- A set  $C \subset \mathbb{E}$  is **closed** if its complement  $\mathbb{E} \setminus C$  is open.
- The **closure** of a set  $C \subset \mathbb{E}$  is

$$\text{cl } C = \{u \in \mathbb{E} : \exists \{u^k\} \subset C \text{ s.t. } \lim_{k \rightarrow \infty} u^k = u\}.$$

- The **interior** of a set  $C \subset \mathbb{E}$  is

$$\text{int } C = \{u \in C : \exists \epsilon > 0 \text{ s.t. } B_\epsilon(u) \subset C\}.$$



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- The **interior** of a set  $C \subset \mathbb{E}$  is

$$\text{int } C = \{u \in C : \exists \epsilon > 0 \text{ s.t. } B_\epsilon(u) \subset C\}.$$

- The **relative interior** of a convex set  $C \subset \mathbb{E}$  is

$$\text{ri } C = \{u \in C : \forall v \in C, \exists \alpha > 1 \text{ s.t. } v + \alpha(u - v) \in C\}.$$

### Convex Set

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The following operations preserve the convexity:

- Intersection:  $C_1 \cap C_2$
- Summation:  $C_1 + C_2 := \{u^1 + u^2 : u^1 \in C_1, u^2 \in C_2\}$
- Closure:  $\text{cl } C$
- Interior:  $\text{int } C$

– The union of convex sets is not convex in general.





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- Interior:  $\text{int } C$

– The union of convex sets is not convex in general.

– *Polyhedral sets* are always convex; *cones* are not necessarily convex.

### Convex cone

$C$  is a **cone** if  $C = \alpha C$  for any  $\alpha > 0$ .  $C$  is a **convex cone** if  $C$  is a cone and is convex as well.

Convex Set

Convex Function

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Subdifferential

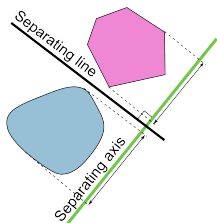
Convex Conjugate

Duality Theory

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## Separation of convex sets



### Theorem (separation of convex sets)

Let  $C_1, C_2$  be nonempty convex subsets in  $\mathbb{E}$  s.t.  $C_1 \cap C_2 = \emptyset$  and  $C_1$  is open. Then there exists a hyperplane separating  $C_1$  and  $C_2$ , i.e.  $\exists v \in \mathbb{E}, v \neq 0, \alpha \in \mathbb{R}$  s.t.

$$\langle v, u^1 \rangle \geq \alpha \geq \langle v, u^2 \rangle, \quad \forall u^1 \in C_1, u^2 \in C_2.$$

Proof: on board.





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Proof: on board.

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## Remarks

- 1 The proof works in any real Hilbert space.
- 2 Corollary: In a real Hilbert space, any (strongly) closed convex subset  $C$  is weakly closed.



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# Convex Function



- An **extended real-valued function**  $J$  maps from  $\mathbb{E}$  to  $\overline{\mathbb{R}} := \mathbb{R} \cup \{\infty\}$ .
- The **domain** of  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is

$$\text{dom } J = \{u \in \mathbb{E} : J(u) < \infty\}.$$

- The function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is **proper** if  $\text{dom } J \neq \emptyset$ .

### Definition

We say  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is a **convex function** if

- 1  $\text{dom } J$  is a convex set.
- 2 For all  $u, v \in \text{dom } J$  and  $\alpha \in [0, 1]$  it holds that

$$J(\alpha u + (1 - \alpha)v) \leq \alpha J(u) + (1 - \alpha)J(v).$$

We say  $J$  is **strictly convex** if the above inequality is strict for all  $\alpha \in (0, 1)$  and  $u \neq v$ .

# Examples

- $J_{data}(u) = \|u - f\|_q^q$  where  $q \geq 1$  and  $\|\cdot\|_q$  is the  $\ell^q$ -norm.
- $J_{regu}(u) = \|Ku\|_q^q$  where  $K$  is linear transform.
- $J(u) = J_{data}(u) + \alpha J_{regu}(u)$  where  $\alpha > 0$ .





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- $J(u) = J_{data}(u) + \alpha J_{regu}(u)$  where  $\alpha > 0$ .
- **Indicator function:**

$$\delta_C(u) = \begin{cases} 0 & \text{if } u \in C, \\ \infty & \text{otherwise,} \end{cases}$$

where  $C$  is a convex subset of  $\mathbb{E}$ .

- Alternative formulation of constrained optimization:

$$\min J(u) \text{ over } u \in C. \Leftrightarrow \min J(u) + \delta_C(u) \text{ over } u \in \mathbb{E}.$$



(As exercises)

- Any norm (over a normed vector space) is a convex function.
- $J$  is a convex function and  $K$  is a linear transform  $\Rightarrow J(K\cdot)$  is convex function.
- (Jensen's inequality)  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is convex iff

$$J\left(\sum_{i=1}^n \alpha_i u^i\right) \leq \sum_{i=1}^n \alpha_i J(u^i),$$

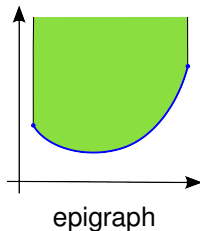
whenever  $\{u^i\}_{i=1}^n \subset \mathbb{E}$ ,  $\{\alpha_i\}_{i=1}^n \subset [0, 1]$ ,  $\sum_{i=1}^n \alpha_i = 1$ .

# Epigraph

## Definition

The **epigraph** of a proper function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is

$$\text{epi } J = \{(u, \alpha) \in \mathbb{E} \times \mathbb{R} : J(u) \leq \alpha\}.$$



## Theorem

A proper function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is convex (resp. strictly convex) iff  $\text{epi } J$  is a convex (resp. strictly convex) set.

Proof: as exercise.







## Definition

Assume  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  with  $\text{ri dom } J \neq \emptyset$ . We say  $J$  is **locally Lipschitz** at  $u \in \text{ri dom } J$  with modulus  $L_u > 0$  if there exists  $\epsilon > 0$  s.t.

$$|J(u^1) - J(u^2)| \leq L_u \|u^1 - u^2\| \quad \forall u^1, u^2 \in B_\epsilon(u) \cap \text{ri dom } J.$$

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## Theorem

A proper convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is locally Lipschitz at any  $u \in \text{ri dom } J$ .

Proof: on board.

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## Global vs. Local minimizers

Recall the optimization of  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ :

$$\text{minimize } J(u) \quad \text{over } u \in \mathbb{E}.$$

### Definition

- 1  $u^* \in \mathbb{E}$  is a **global minimizer** if  $J(u^*) \leq J(u)$  for all  $u \in \mathbb{E}$ .
- 2  $u^*$  is a **local minimizer** if  $\exists \epsilon > 0$  s.t.  $J(u^*) \leq J(u)$  for all  $u \in B_\epsilon(u^*)$ .
- 3 In the above definitions, a global/local minimizer is **strict** if  $J(u^*) \leq J(u)$  is replaced by strict inequality  $J(u^*) < J(u)$ .



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Recall the optimization of  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ :

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### Theorem

For any proper convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ , if  $u^* \in \text{dom } J$  is a local minimizer of  $J$ , then it is also a global minimizer.

Proof: on board.





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# Existence of Minimizer

# Does a minimizer always exist?

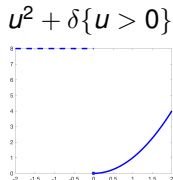
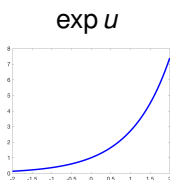
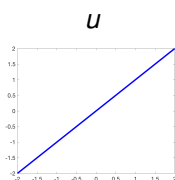


- Consider

$$\text{minimize } J(u) \quad \text{over } u \in \mathbb{E},$$

where  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is a proper, convex function.

- Some counterexamples for  $J : \mathbb{R} \rightarrow \overline{\mathbb{R}}$ :



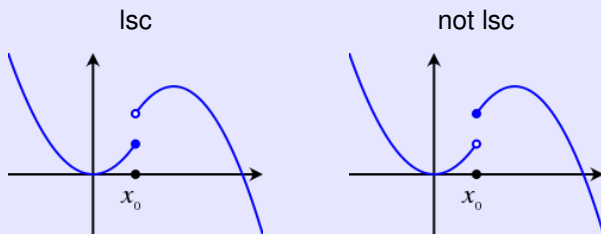
- We shall formalize our observations and derive sufficient conditions for existence.

# Sufficient conditions for existence

## Definition

- 1  $J$  is **bounded from below** if  $J(\cdot) \geq C$  for some  $C \in \mathbb{R}$ .
- 2  $J$  is **coercive** if  $J(u) \rightarrow \infty$  whenever  $\|u\| \rightarrow \infty$ .
  - Proposition:  $J$  is coercive if  $\text{dom } J$  is bounded.
- 3  $J$  is **lower-semicontinuous** (lsc) if

$$J(u^*) \leq \liminf_{u \rightarrow u^*} J(u).$$



- Proposition:  $J$  is lsc iff  $\text{epi } J$  is closed.



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## Theorem

Any proper function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ , which is bounded from below, coercive, and lsc, has a (global) minimizer.

Proof: on board.





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Proof: on board.

### Remarks for infinite dimensions

- 1 Weak compactness in reflexive Banach (e.g. Hilbert) sp.
- 2  $J$  is convex and strongly lsc  $\Rightarrow J$  is weakly lsc



- Recall that a function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is strictly convex if

$$J(\alpha u + (1 - \alpha)v) < \alpha J(u) + (1 - \alpha)J(v),$$

for all  $u, v \in \text{dom } J$ ,  $u \neq v$ ,  $\alpha \in (0, 1)$ .

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## Theorem

The minimizer of a strictly convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is unique.

Proof: on board.



# Subdifferential

Convex Set

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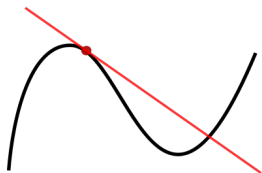
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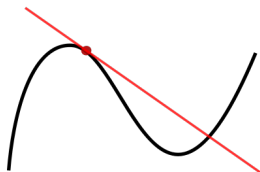
## Definition

$J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is called (Fréchet) **differentiable** at  $u \in \text{int dom } J$  and  $\nabla J(u) \in \mathbb{E}$  is the (Fréchet) **differential** of  $J$  at  $u$  if

$$\lim_{h \rightarrow 0, h \in (\text{dom } J) - u} \frac{J(u + h) - J(u) - \langle \nabla J(u), h \rangle}{\|h\|} = 0.$$

$J$  is said **continuously differentiable** at  $u \in \text{int dom } J$  if  $\nabla J(\cdot)$  is continuous on  $\text{dom } J \cap B_\epsilon(u)$  for some  $\epsilon > 0$ .





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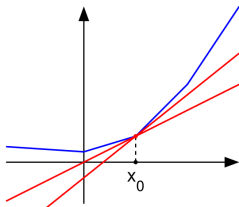
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## Remark

In functional analysis,  $\nabla J(u)$  is treated as a *dual* object in  $\mathbb{E}^*$ , and  $\langle \nabla J(u), h \rangle_{\mathbb{E}^*, \mathbb{E}}$  as *duality pairing*.

## Subdifferential

Now we generalize differentiability from differentiable functions to nonsmooth (convex) functions.



### Definition

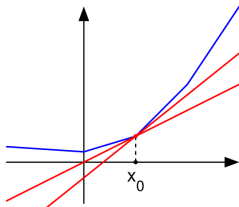
The **subdifferential** of a convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  at  $u \in \text{dom } J$  is defined by

$$\partial J(u) = \{\xi \in \mathbb{E} : J(v) \geq J(u) + \langle \xi, v - u \rangle\}.$$



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$$\partial J(u) = \{\xi \in \mathbb{E} : J(v) \geq J(u) + \langle \xi, v - u \rangle\}.$$

### Geometric interpretation

$\xi \in \partial J(u)$  iff  $(\xi, -1)$  is a normal vector for the supporting hyperplane of  $\text{epi } J$  at  $(u, J(u))$ .



## Basic facts

- 1  $\partial J(\cdot)$  is a **set-valued map**.
- 2 If  $J$  is cont. differentiable at  $u$ , then  $\partial J(u) = \{\nabla J(u)\}$ .



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### Examples (as exercises)

- 1  $u \in \mathbb{R}^n \mapsto \|u\|_1$ .
- 2  $u \in \mathbb{R}^n \mapsto \|u\|_\infty$ .
- 3  $X \in \mathbb{R}^{n \times n} \mapsto \|X\|_{1,2} = \sum_i \left( \sum_j |X_{i,j}|^2 \right)^{1/2}$ .
- 4  $X \in \mathbb{R}^{n \times n} \mapsto \|X\|_{nuc} = \sum_i \sigma_i(X)$  (sum of singular values).
- 5 Given a closed convex subset  $C \subset \mathbb{E}$  and  $u \in C$ ,

$$\partial \delta_C(u) = N_C(u) = \{\xi \in \mathbb{E} : \langle \xi, v - u \rangle \leq 0 \forall v \in C\},$$

known as the **normal cone** of  $C$  at  $u$ .

## Theorem (chain rule under linear transform)

Let  $\tilde{J}(\cdot) = J(K\cdot)$  with some convex function  $J$  and linear transform  $K$ . Then

$$\partial\tilde{J}(u) = K^T \partial J(Ku)$$

for any  $u \in \text{ri dom } J$ .

Example:  $J(u) = \|Ku\|_1 \Rightarrow \partial J(u) = K^T \partial \|\cdot\|_1(Ku)$ .



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## Theorem (chain rule under linear transform)

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$$\partial\tilde{J}(u) = K^\top \partial J(Ku)$$

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Example:  $J(u) = \|Ku\|_1 \Rightarrow \partial J(u) = K^\top \partial \|\cdot\|_1(Ku)$ .

## Theorem (summation rule)

If  $J(\cdot) = J_1(\cdot) + J_2(\cdot)$  for some convex functions  $J_1$  and  $J_2$ , then

$$\partial\tilde{J}(u) = \partial J_1(u) + \partial J_2(u)$$

for any  $u \in \text{ri dom } J_1 \cap \text{ri dom } J_2$ .

Warning: not true if  $J_1$  or  $J_2$  is non-convex, e.g.  $0 = |\cdot| + (-|\cdot|)$ .

## Properties of subdifferential map

### Theorem

Let  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be a convex function. Then  $\partial J$  is a **monotone operator**, i.e.  $\forall u^1, u^2 \in \text{dom } J, \xi^1 \in \partial J(u^1), \xi^2 \in \partial J(u^2)$  :

$$\langle \xi^1 - \xi^2, u^1 - u^2 \rangle \geq 0.$$

Proof: on board.



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Proof: on board.

### Theorem

Let  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be a convex function. Then for any  $u \in \text{int dom } J$ ,  $\partial J(u)$  is a nonempty, compact, and convex subset.

Proof: on board.



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### Theorem

Let  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be a convex function. Then  $\partial J$  is a **monotone operator**, i.e.  $\forall u^1, u^2 \in \text{dom } J, \xi^1 \in \partial J(u^1), \xi^2 \in \partial J(u^2)$  :

$$\langle \xi^1 - \xi^2, u^1 - u^2 \rangle \geq 0.$$

Proof: on board.

### Theorem

Let  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be a convex function. Then for any  $u \in \text{int dom } J$ ,  $\partial J(u)$  is a nonempty, compact, and convex subset.

Proof: on board.

### Theorem

Let  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be a proper, convex, lsc function. Then the set-valued map  $\partial J(\cdot)$  is **closed**, i.e.  $\xi^* \in \partial J(u^*)$  whenever

$$\exists (u^k, \xi^k) \rightarrow (u^*, \xi^*) \in (\text{ri dom } J) \times \mathbb{E} \text{ s.t. } \xi^k \in \partial J(u^k) \forall k.$$

Proof: on board.



# Optimality condition

## Theorem

Given any proper convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ , the sufficient and necessary condition for  $u^*$  being a (global) minimizer for  $J$  is

$$0 \in \partial J(u^*).$$

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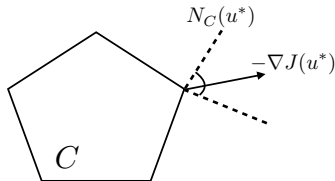
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### Constrained optimization as special case

If  $\tilde{J}(u) = J(u) + \delta_C(u)$  with convex function  $J : \mathbb{E} \rightarrow \mathbb{R}$  and closed convex subset  $C \in \mathbb{E}$ , then  $0 \in \partial \tilde{J}(u^*) \rightsquigarrow$

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### Remark

$0 \in \partial J(u^*) + N_C(u^*)$  is a *geometric* optimality condition. Further characterization relies on the algebraic representation of  $N_C(u^*)$ , e.g. the Karush-Kuhn-Tucker (KKT) conditions under certain constraint qualifications.





# Convex Conjugate

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# Legendre-Fenchel transform

## Definition

Given a convex function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ , the **convex conjugate** of  $J$  is defined by

$$J^*(p) = \sup_{u \in \mathbb{E}} \langle u, p \rangle - J(u).$$

Convex Analysis

Tao Wu  
Thomas Möllenhoff  
Emanuel Laude



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## Examples (as exercises)

- 1  $J(\cdot) = \langle w, \cdot \rangle \Rightarrow J^*(\cdot) = \delta\{\cdot = w\}. (w \in \mathbb{E})$
- 2  $J(\cdot) = \frac{1}{q} \|\cdot\|_q^q \Rightarrow J^*(\cdot) = \frac{1}{q'} \|\cdot\|_{q'}^{q'}. (0 < q < 1, \frac{1}{q} + \frac{1}{q'} = 1)$
- 3  $J(\cdot) = \|\cdot\| \Rightarrow J^*(\cdot) = \delta\{\|\cdot\|_* \leq 1\}. (\|\cdot\|_* \text{ is the dual norm of } \|\cdot\|, \text{ i.e. } \|v\|_* = \sup_{\|u\| \leq 1} \langle u, v \rangle)$
- 4  $J(\cdot) = \delta\{\|\cdot\|_* \leq 1\} \Rightarrow J^*(\cdot) = \|\cdot\|.$



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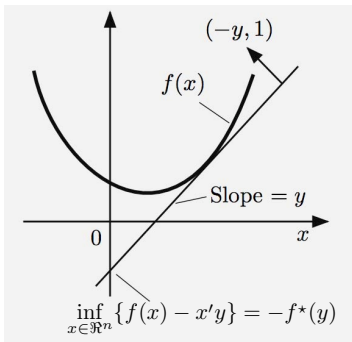
## Basic facts

- Scalar multiplication:  $\tilde{J}(\cdot) = \alpha J(\cdot) \Rightarrow \tilde{J}^*(\cdot) = \alpha J^*(\cdot/\alpha).$
- Translation:  $\tilde{J}(\cdot) = J(\cdot - z) \Rightarrow \tilde{J}^*(\cdot) = J^*(\cdot) + \langle \cdot, z \rangle.$



## Geometric interpretation

Convex conjugation maps:  
(non-vertical) supporting hyperplane of the epigraph  
to:  
intersection with the vertical axis.



Courtesy of Bertsekas





## Theorem (Fenchel-Young inequality)

For all  $u \in \text{dom } J$ ,  $p \in \text{dom } J^*$ , we have

$$J(u) + J^*(p) \geq \langle u, p \rangle.$$

The equality holds iff  $p \in \partial J(u)$ .

Proof:  $J(u) + J^*(p) \geq \langle u, p \rangle$  follows directly from the definition of convex conjugate;  $p \in \partial J(u)$  is the sufficient and necessary condition for:  $u = \arg \min_{v \in \mathbb{E}} J(v) - \langle v, p \rangle$ .

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## Theorem

Assume  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  and  $J^{**} = (J^*)^*$  is the **biconjugate** of  $J$ .

In general:

- 1  $J^{**}(\cdot) \leq J(\cdot)$ .
- 2  $J^*$  is convex and lsc.

If  $J$  is proper, convex, and lsc, then:

- 3  $J^{**}(\cdot) = J(\cdot)$ .
- 4  $p \in \partial J(u)$  iff  $u \in \partial J^*(p)$ .

Proof: on board.

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### Definition

$J : \mathbb{E} \rightarrow \mathbb{R}$  is said to be  $\mu$ -strongly convex if  $\exists \mu > 0$  s.t.  
 $J(\cdot) - \frac{\mu}{2} \|\cdot\|^2$  is convex.



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## Regularity of $J$ and $J^*$

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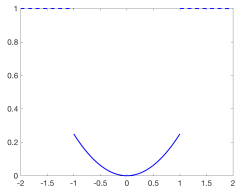
### Theorem

Assume that  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is proper, convex, and lsc. Then  $J$  is  $\mu$ -strongly convex iff  $J^*$  has  $\frac{1}{\mu}$ -Lipschitz gradient.

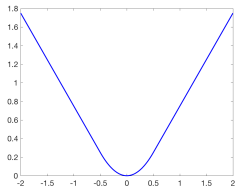
Proof: on board.



$J =$  truncated quadratic



$J^* =$  Huber function





# Duality Theory

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# Fenchel-Rockafellar duality

- Consider

$$\min_{u \in \mathbb{R}^n} F(Ku) + G(u),$$

where  $K \in \mathbb{R}^{m \times n}$ , and  $F, G$  are proper, convex, and lsc.



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- The **weak duality** always holds:

$$\begin{aligned} \mathcal{P}^* &= \min_{u \in \mathbb{R}^n} F(Ku) + G(u) = \min_u \sup_p \langle p, Ku \rangle - F^*(p) + G(u) \\ &\geq \sup_p \inf_u \langle K^\top p, u \rangle + G(u) - F^*(p) \\ &= \sup_p -G^*(-K^\top p) - F^*(p) = \mathcal{D}^*. \end{aligned}$$



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- Define the **duality gap**:

$$\mathcal{G}(u, p) = F(Ku) + G(u) + G^*(-K^\top p) + F^*(p).$$

Note that  $\mathcal{G}(u, p) = 0$  is an optimality criterion.

# Fenchel-Rockafellar duality

- $\mathcal{G}(u^*, p^*) = 0 \Leftrightarrow \mathcal{P}^* = \mathcal{D}^* \Leftrightarrow (u^*, p^*)$  solves the **saddle point problem** with  $\mathcal{L}(u, p) := \langle p, Ku \rangle - F^*(p) + G(u)$ :

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### Theorem (Fenchel-Rockafellar duality)

Assume  $\exists \bar{u} \in \text{dom } G$  s.t.  $F$  is continuous at  $K\bar{u}$ . Then the **strong duality** holds:  $\mathcal{P}^* = \mathcal{D}^*$ . Moreover,  $(u^*, p^*)$  is the optimal solution pair iff

$$\begin{cases} Ku^* \in \partial F^*(p^*), \\ -K^\top p^* \in \partial G(u^*). \end{cases}$$

Proof: on board.



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## Application: Total-variation image restoration

- Primal problem (let  $\alpha > 0$ ,  $q \in [1, \infty]$ ,  $\Omega \subset \mathbb{R}^d$ ,  $f \in \mathbb{R}^\Omega$ ):

$$\min_{u \in \mathbb{R}^\Omega} \alpha \|\nabla u\|_{1,q} + \frac{1}{2} \|u - f\|^2.$$

Here  $\|p\|_{1,q} = \sum_{j \in \Omega} |p_j|_{\ell^q}$  for each  $p \in (\mathbb{R}^\Omega)^d$ .



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- Dual problem:

$$\min_p \frac{1}{2} \|\nabla^\top p - f\|^2 + \delta\{\|p\|_{\infty, q'} \leq \alpha\}.$$





# Proximal Operator

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## Definition

Given a proper, convex, lsc function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$ , we define the **proximal operator** of  $J$  by

$$\text{prox}_{\tau J}(v) = \arg \min_u J(u) + \frac{1}{2\tau} \|u - v\|^2.$$

Note: The above minimization always has a unique minimizer.



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## Proximal operator in algorithms

Let us solve the convex optimization:

$$\min_u F(u) + G(u),$$

where  $G$  is cont'ly differentiable but  $F$  is non-differentiable.

The **proximal gradient** iteration appears as:

$$u^{k+1} = \text{prox}_{\tau F}(u^k - \tau \nabla G(u^k)).$$

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## Observations

① By checking the optimality condition,

$$u = \text{prox}_{\tau J}(v) \Leftrightarrow 0 \in \tau \partial J(u) + u - v \Leftrightarrow u = (I + \tau \partial J)^{-1}(v).$$

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- ③ Derivation of proximal gradient algorithm:

$$\begin{aligned} u^* &\in \arg \min_u F(u) + G(u) \\ &\Leftrightarrow 0 \in \partial F(u^*) + \nabla G(u^*) \\ &\Leftrightarrow u^* + \tau \partial F(u^*) \in u^* - \tau \nabla G(u^*) \\ &\Leftrightarrow u^* = (I + \tau \partial F)^{-1}(u^* - \tau \nabla G(u^*)) \\ &\rightsquigarrow u^{k+1} = \text{prox}_{\tau F}(u^k - \tau \nabla G(u^k)). \end{aligned}$$

## Logistic regression (programming exercise)



- MNIST dataset<sup>1</sup> - handwritten digit recognition.
- Train classifier on training set; Evaluate on test set.
- Conv. neural network: 0.23%; **Logistic regression**: 10%.



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- **Softmax** function:

$$\mathcal{P}(Y_n = k | X_{n,\cdot}, W) = \frac{\exp(\langle W_{k,\cdot}, X_{n,\cdot} \rangle)}{\sum_{k=1}^K \exp(\langle W_{k,\cdot}, X_{n,\cdot} \rangle)}$$

- Minimize negative log-likelihood + regularizer:

$$\min_W \alpha \|W\|_1 - \frac{1}{N} \sum_{n=1}^N \sum_{k=1}^K \mathbf{1}\{Y_n = k\} \log \mathcal{P}(Y_n = k | X_{n,\cdot}, W).$$

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## Examples

① Indicator function: Let  $C$  be a closed, convex subset  $\Rightarrow$

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- ③ Quadratic approximation:

$$\tilde{J}(\cdot) := J(\bar{u}) + \langle \nabla J(\bar{u}), \cdot - \bar{u} \rangle + \frac{1}{2} \langle \nabla^2 J(\bar{u})(\cdot - \bar{u}), \cdot - \bar{u} \rangle \Rightarrow$$

$$\begin{aligned}\text{prox}_{\tau\tilde{J}}(\bar{u}) &= \arg \min_u \frac{1}{2\tau} \|u - \bar{u}\|^2 + \langle \nabla J(\bar{u}), u - \bar{u} \rangle \\ &\quad + \frac{1}{2} \langle \nabla^2 J(\bar{u})(u - \bar{u}), u - \bar{u} \rangle \\ &= \bar{u} - (\nabla^2 J(\bar{u}) + \frac{1}{\tau} I)^{-1} \nabla J(\bar{u}). \quad (\text{damped Newton step})\end{aligned}$$





## Theorem (Moreau identity)

Let  $\tau > 0$  and  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be proper, convex, and lsc. Then the following identity holds:

$$\text{id}(\cdot) = \text{prox}_{\tau J}(\cdot) + \tau \text{prox}_{\frac{1}{\tau} J^*}(\cdot/\tau).$$

In particular,  $\tau = 1 \Rightarrow \text{id}(\cdot) = \text{prox}_J(\cdot) + \text{prox}_{J^*}(\cdot)$ .

Proof:

$$\begin{aligned} v &= \tau \text{prox}_{\frac{1}{\tau} J^*}(u/\tau) \\ \Leftrightarrow \left( I + \frac{1}{\tau} \partial J^* \right)^{-1} (u/\tau) &\ni v/\tau \\ \Leftrightarrow \partial J^*(v/\tau) &\ni u - v \\ \Leftrightarrow v/\tau &\in \partial J(u - v) \\ \Leftrightarrow u - v &= (I + \tau \partial J)^{-1}(u) = \text{prox}_{\tau J}(u). \end{aligned}$$



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## Remark

The Moreau identity suggests that if one of  $\text{prox}_J(\cdot)$  and  $\text{prox}_{J^*}(\cdot)$  is computable, so is the other.

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## Definition

Let  $F, G : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be proper, convex, and lsc. The **infimal convolution** (or inf convolution) of  $F$  and  $G$  is defined by

$$(F \square G)(\cdot) = \inf_{u \in \mathbb{E}} \{F(\cdot - u) + G(u)\},$$

with  $\text{dom}(F \square G) = \text{dom } F + \text{dom } G$ .

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## Theorem

Let  $F, G : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  be proper, convex, and lsc. Then

$$(F \square G)^*(\cdot) = F^*(\cdot) + G^*(\cdot).$$

Proof: on board.

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## Remark

Analogy between inf convolution (under convex conjugation) and convolution (under Fourier transform):  $\widehat{F * G}(\cdot) = \widehat{F}(\cdot) \widehat{G}(\cdot)$ .

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## Definition

The **Moreau envelope** of a proper, convex, lsc function  $J : \mathbb{E} \rightarrow \overline{\mathbb{R}}$  is defined for each  $u \in \mathbb{E}$  by

$$\begin{aligned}\mathcal{M}_{\alpha J}(u) &:= \left( J \square \left( \frac{1}{2\alpha} \|\cdot\|^2 \right) \right) (u) \\ &= \inf_{v \in \mathbb{E}} \left\{ J(v) + \frac{1}{2\alpha} \|v - u\|^2 \right\} \\ &= J(\text{prox}_{\alpha J}(u)) + \frac{1}{2\alpha} \|\text{prox}_{\alpha J}(u) - u\|^2.\end{aligned}$$



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## Example

$J : u \in \mathbb{R} \mapsto |u| \Rightarrow \mathcal{M}_{\alpha J}$  is Huber function:

$$\mathcal{M}_{\alpha J}(u) = \begin{cases} u^2/(2\alpha) & \text{if } |u| \leq \alpha, \\ |u| - \alpha/2 & \text{if } |u| > \alpha. \end{cases}$$

Observation:  $\mathcal{M}_{\alpha J}$  does smoothing/regularization on  $J$ .

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- Recall the theorem:  $(F \square G)^*(\cdot) = F^*(\cdot) + G^*(\cdot) \Rightarrow$

$$(\mathcal{M}_{\alpha J})^* = J^* + \left(\frac{1}{2\alpha} \|\cdot\|^2\right)^* = J^* + \frac{\alpha}{2} \|\cdot\|^2.$$





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- Recall the theorem:  $J$  is  $\mu$ -strongly convex iff  $J^*$  has  $\frac{1}{\mu}$ -Lipschitz gradient.  $\Rightarrow$   
 $\mathcal{M}_{\alpha J}$  has  $\frac{1}{\alpha}$ -Lipschitz gradient.





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 $\mathcal{M}_{\alpha J}$  has  $\frac{1}{\alpha}$ -Lipschitz gradient.

- $\nabla \mathcal{M}_{\alpha J}$  can be calculated as:

$$\begin{aligned} p = \nabla \mathcal{M}_{\alpha J}(u) &\Leftrightarrow u \in \partial(\mathcal{M}_{\alpha J})^*(p) = \partial J^*(p) + \alpha p \\ &\Leftrightarrow u - \alpha p \in \partial J^*(p) \Leftrightarrow \partial J(u - \alpha p) \ni p \\ &\Leftrightarrow \alpha \partial J(u - \alpha p) \ni \alpha p \Leftrightarrow (I + \alpha \partial J)(u - \alpha p) \ni u \\ &\Leftrightarrow u - \alpha p = (I + \alpha \partial J)^{-1} u = \text{prox}_{\alpha J}(u) \\ &\Leftrightarrow \nabla \mathcal{M}_{\alpha J}(u) = \frac{1}{\alpha} (u - \text{prox}_{\alpha J}(u)). \end{aligned}$$