

Machine Learning Basics

























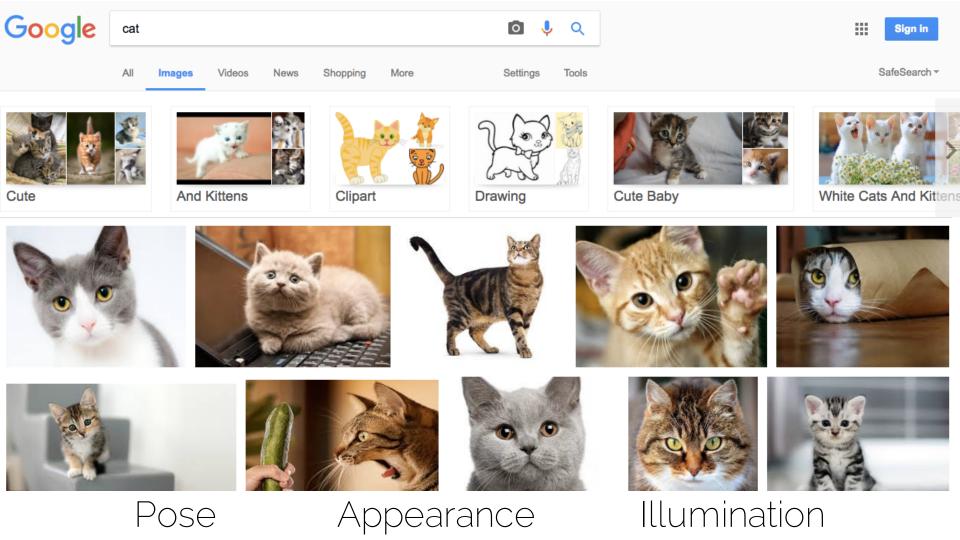


















Occlusions



Background clutter



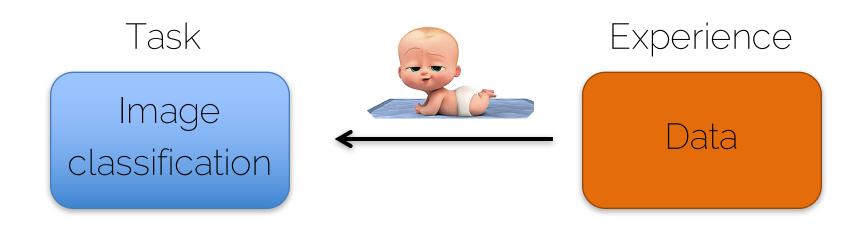




Representation



How can we learn to perform image classification?



Unsupervised learning

- No label or target class
- Find out properties of the structure of the data
- Clustering (k-means, PCA)

Supervised learning

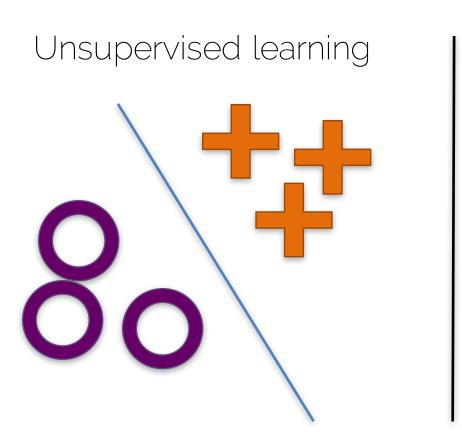
Unsupervised learning

Supervised learning

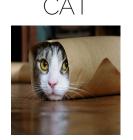
Unsupervised learning

Supervised learning

 Labels or target classes



Supervised learning













DOG

How can we learn to perform image classification?



Experience

Test data

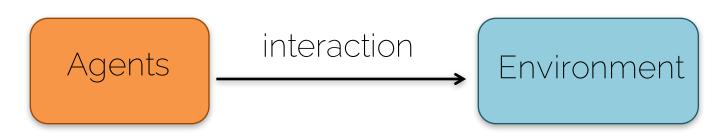
Unsupervised learning



Supervised learning



Reinforcement learning



Unsupervised learning



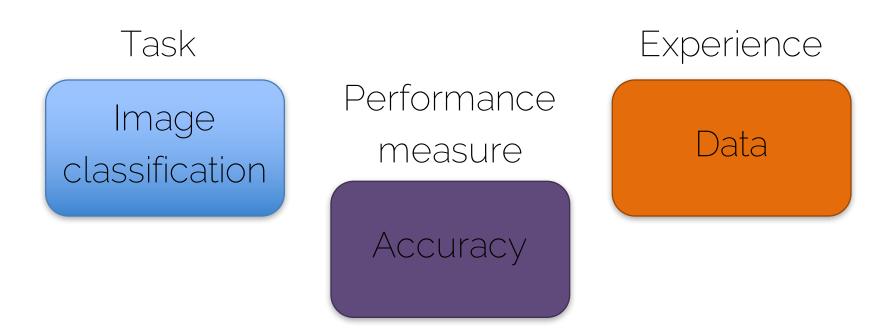
Supervised learning



Reinforcement learning



How can we learn to perform image classification?





A simple classifier











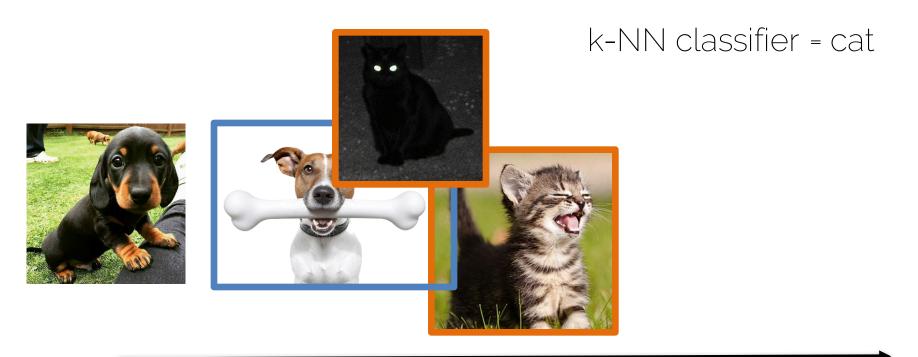




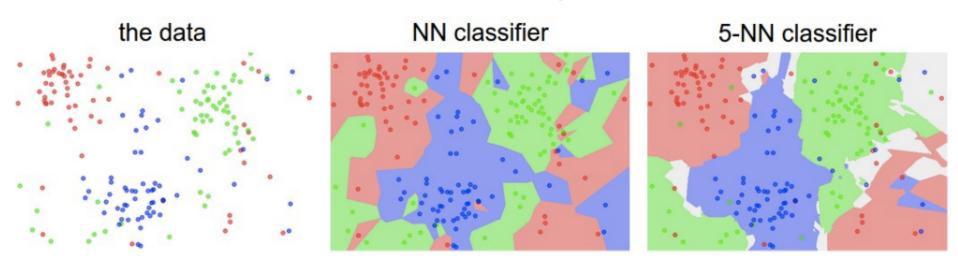








distance



What is the performance on training data for NN classifier?

What classifier is more likely to perform best on test data?

Courtesy of Stanford course cs231n

Hyperparameters

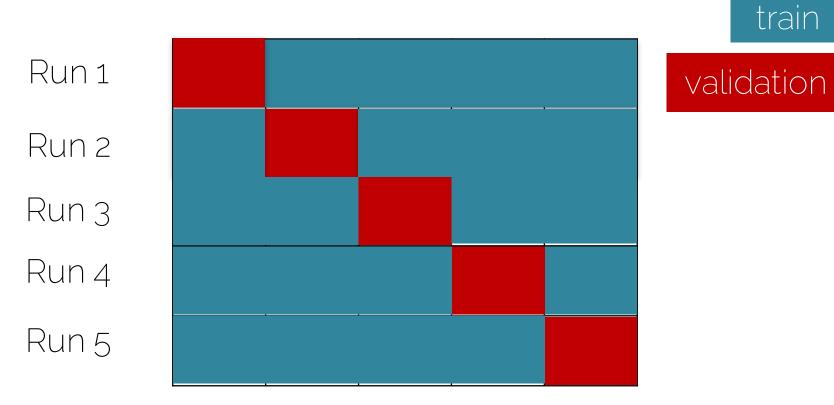
Distance (L1, L2)

k (number of neighbors)

These parameters are problem dependent.

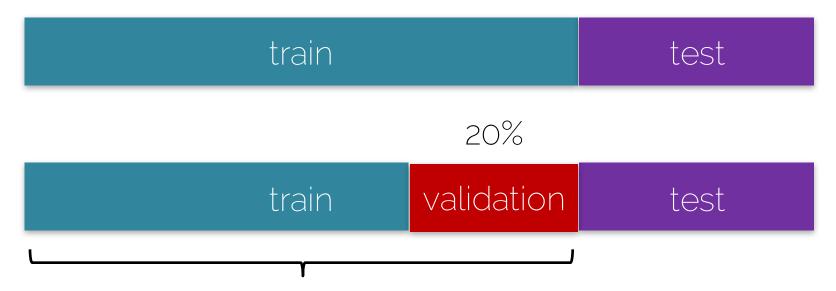
How do we choose these hyperparameters?

Cross validation



Split the training data into N folds

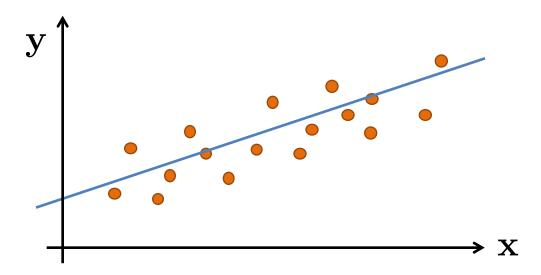
Cross validation



Find your hyperparameters



- Supervised learning
- Find a linear model that explains a target ${f y}$ given the inputs ${f X}$



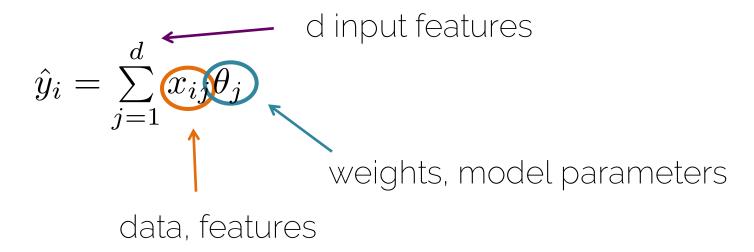
Training



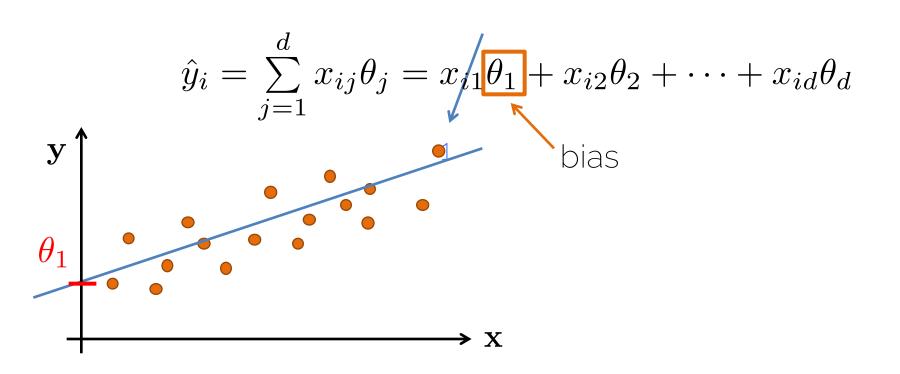
Testing

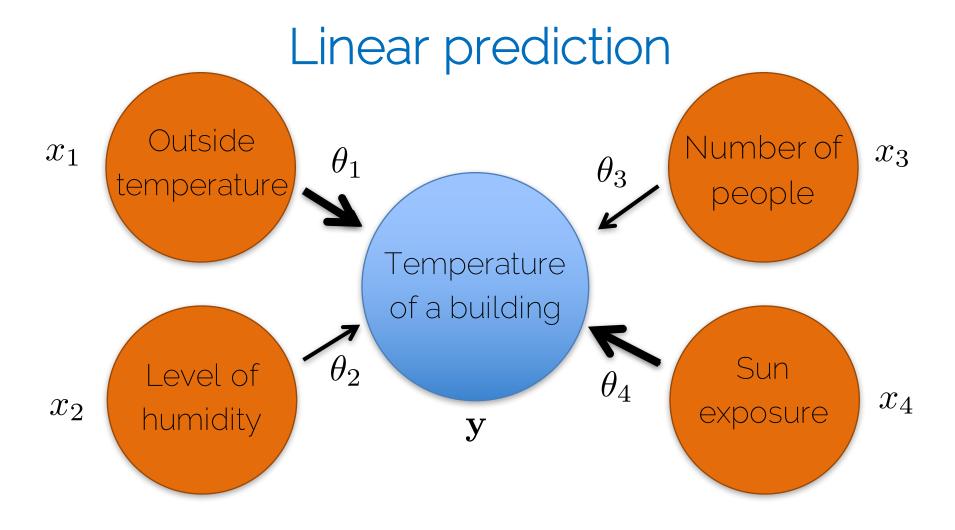


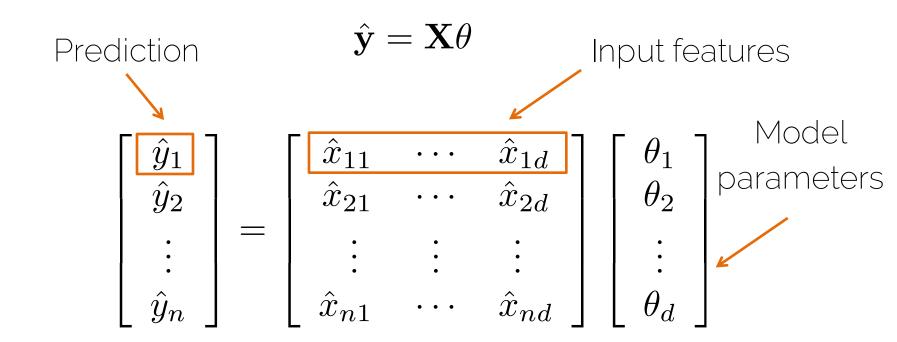
A linear model is expressed in the form

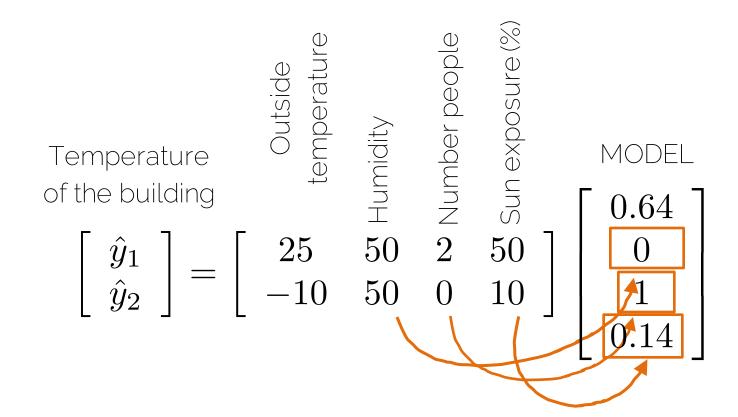


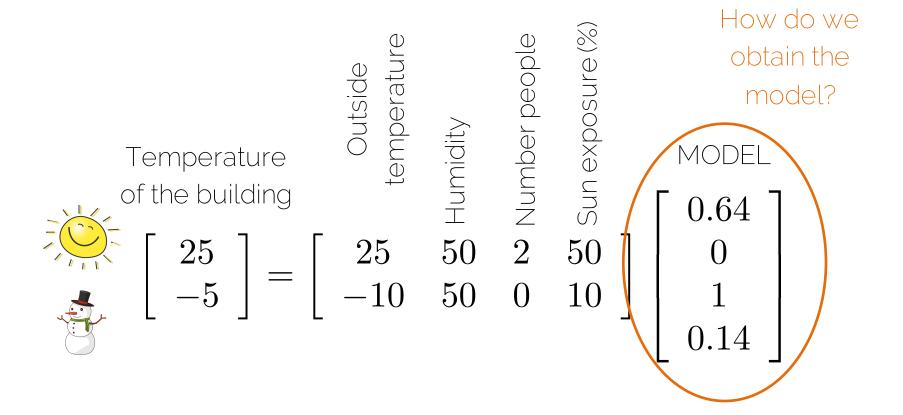
A linear model is expressed in the form

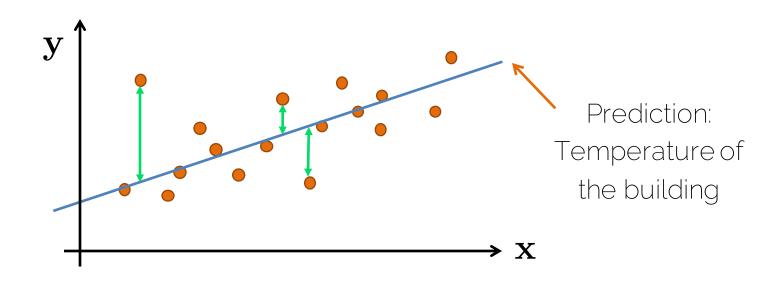


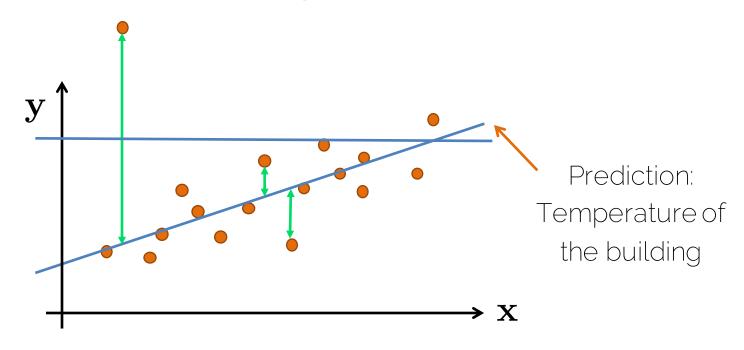


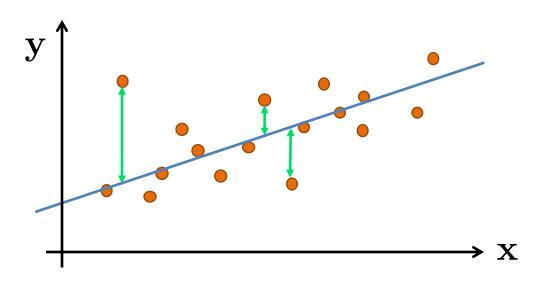












Minimizing

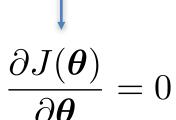
$$J(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

Objective function
Energy
Loss

Optimization

$$J(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2 = \frac{1}{n} \sum_{i=1}^{n} (\mathbf{x}_i \boldsymbol{\theta} - y_i)^2$$

$$\min_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \min_{\boldsymbol{\theta}} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})^T (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})$$



Optimization

$$\mathbf{v} = (\mathbf{v}\mathbf{\rho} - \mathbf{v})^T (\mathbf{v}\mathbf{\rho} - \mathbf{v})^T$$

$$J(\boldsymbol{\theta}) = (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})^T (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})$$

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = \frac{\partial}{\partial \boldsymbol{\theta}} (\boldsymbol{\theta}^T \mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - 2\boldsymbol{\theta}^T \mathbf{X}^T \mathbf{y} + \mathbf{y}^T \mathbf{y})$$

$$\frac{\partial \boldsymbol{\theta}^T \mathbf{A} \boldsymbol{\theta}}{\partial \boldsymbol{\theta}} = 2\mathbf{A}^T \boldsymbol{\theta}$$

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = \mathbf{A}^T \mathbf{\theta}$$

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = 2\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - 2\mathbf{X}^T \mathbf{y} = 0$$

Optimization

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = 2\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - 2\mathbf{X}^T \mathbf{y} = 0$$

$$oldsymbol{ heta} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$$
Inputs: Outside temperature, number of people...

Output:

Temperature of the building

Is this the best estimate?

Mean squared error (MSE)

$$J(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$



Maximum Likelihood

 $p_{data}(\mathbf{x})$ True underlying distribution



 $p_{model}(\mathbf{x}; \boldsymbol{\theta})$ Parametric family of distributions

Controlled by a parameter

 A method of estimating the parameters of a statistical model given observations,

$$p_{model}(\mathbb{X};oldsymbol{ heta})$$

Observations from $p_{data}(\mathbf{x})$

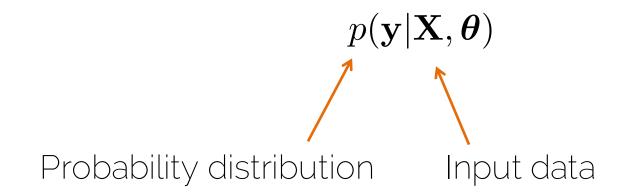
• A method of estimating the parameters of a statistical model given observations, by finding the parameter values that maximize the likelihood of making the observations given the parameters.

$$m{ heta}_{ML} = rg \max_{m{ heta}} p_{model}(\mathbb{X}; m{ heta})$$
 $m{ heta}_{ML} = rg \max_{m{ heta}} \prod_{i=1}^m p_{model}(\mathbf{x}_i; m{ heta})$

$$\boldsymbol{\theta}_{ML} = \arg \max_{\boldsymbol{\theta}} \prod_{i=1} p_{model}(\mathbf{x}_i; \boldsymbol{\theta})$$

$$\boldsymbol{\theta}_{ML} = \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^{l} \log p_{model}(\mathbf{x}_i; \boldsymbol{\theta})$$

Spoiler: Related to softmax loss



$$m{ heta}_{ML} = rg\max_{m{ heta}} p(\mathbf{y}|\mathbf{X}, m{ heta})$$
 i.i.d. =independent and identically distributed

$$\boldsymbol{\theta}_{ML} = \arg\max_{\theta} \sum_{i=1} \log p(y_i|\mathbf{x}_i, \boldsymbol{\theta})$$

Gaussian or Normal distribution
$$p(y_i|\mathbf{x}_i, \boldsymbol{\theta}) \qquad \text{distribution}$$
 Assuming $y_i = \mathcal{N}(\mathbf{x}_i \boldsymbol{\theta}, \sigma^2) = \mathbf{x}_i \boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$
 $x \sim \mathcal{N}(\mu, \sigma^2)$

$$p(y_i|\mathbf{x}_i,\boldsymbol{\theta})$$

Assuming
$$y_i = \mathcal{N}(\mathbf{x}_i \boldsymbol{\theta}, \sigma^2) = \mathbf{x}_i \boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} \qquad x \sim \mathcal{N}(\mu, \sigma^2)$$

Assuming
$$y_i = (2\pi\sigma^2)^{-1/2}e^{-\frac{1}{2\sigma^2}(y_i - \mathbf{x}_i \boldsymbol{\theta})^2}$$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}}e^{-\frac{1}{2\sigma^2}(x - \mu)^2} \qquad x \sim \mathcal{N}(\mu, \sigma^2)$$

$$p(y_i|\mathbf{x}_i,\boldsymbol{\theta}) = (2\pi\sigma^2)^{-1/2}e^{-\frac{1}{2\sigma^2}(y_i-\mathbf{x}_i\boldsymbol{\theta})^2}$$

Assuming
$$y_i = \mathcal{N}(\mathbf{x}_i \boldsymbol{\theta}, \sigma^2) = \mathbf{x}_i \boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} \qquad x \sim \mathcal{N}(\mu, \sigma^2)$$

$$p(y_i|\mathbf{x}_i,\boldsymbol{\theta}) = (2\pi\sigma^2)^{-1/2}e^{-\frac{1}{2\sigma^2}(y_i-\mathbf{x}_i\boldsymbol{\theta})^2}$$

$$\boldsymbol{\theta}_{ML} = \arg\max_{\theta} \sum_{i=1}^{n} \log p(y_i|\mathbf{x}_i, \boldsymbol{\theta})$$

$$\log((2\pi\sigma^2)^{-1/2}e^{-\frac{1}{2\sigma^2}(y_i-\mathbf{x}_i\boldsymbol{\theta})^2})$$
 Matrix notation
$$\log((2\pi\sigma^2)^{-1/2}e^{-\frac{1}{2\sigma^2}(\mathbf{y}-\mathbf{X}\boldsymbol{\theta})^T(\mathbf{y}-\mathbf{X}\boldsymbol{\theta})})$$

$$-\frac{1}{2}\log(2\pi\sigma^2) - \frac{1}{2\sigma^2}(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})$$

$$\boldsymbol{\theta}_{ML} = \arg \max_{\boldsymbol{\theta}} p(\mathbf{y}|\mathbf{X}, \boldsymbol{\theta})$$

$$-\frac{1}{2}\log(2\pi\sigma^2) - \frac{1}{2\sigma^2}(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})$$

$$\frac{\partial}{\partial \boldsymbol{\theta}}$$
 How can we find the estimate of theta?

$$-\frac{1}{2}\log(2\pi\sigma^2) - \frac{1}{2\sigma^2}(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} - \mathbf{X}\boldsymbol{\theta})$$

Can you derive the estimate of sigma?



Regularization and MAP

$$x = [1, 2, 1] \longrightarrow$$
Input = 3 features

$$\theta_1 = [1.5, 0, 0] \longrightarrow \text{Ignores 2 features}$$

$$\theta_2 = [0.25, 0.5, 0.25] \longrightarrow \text{Takes information}$$
 from all features

Loss
$$J(oldsymbol{ heta}) = (\mathbf{y} - \mathbf{X}oldsymbol{ heta})^T (\mathbf{y} - \mathbf{X}oldsymbol{ heta}) + \lambda R(oldsymbol{ heta})$$

L2 regularization
$$\boldsymbol{\theta}^T \boldsymbol{\theta}$$

$$\boldsymbol{\theta}_1^T \boldsymbol{\theta}_1 = 1.5 * 1.5 = 2.25$$

$$\boldsymbol{\theta}_2^T \boldsymbol{\theta}_2 = 0.25^2 + 0.5^2 + 0.25^2 = 0.375$$

$$x = [1, 2, 1]$$
 $\theta_1 = [1.5, 0, 0]$ $\theta_2 = [0.25, 0.5, 0.25]$

Loss
$$J(\boldsymbol{\theta}) = (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) + \lambda R(\boldsymbol{\theta})$$

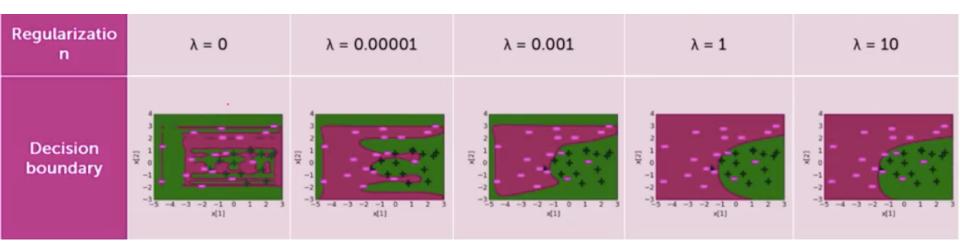
L2 regularization

L1 regularization

Max norm regularization

Dropout

Can you find the relationship between this loss and the Maximum a Posteriori (MAP) estimate?

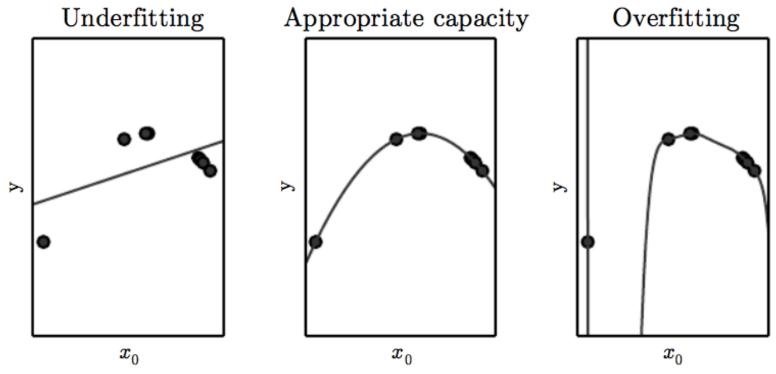


What is the goal of regularization?

What happens to the training error?

Credits: University of Washington

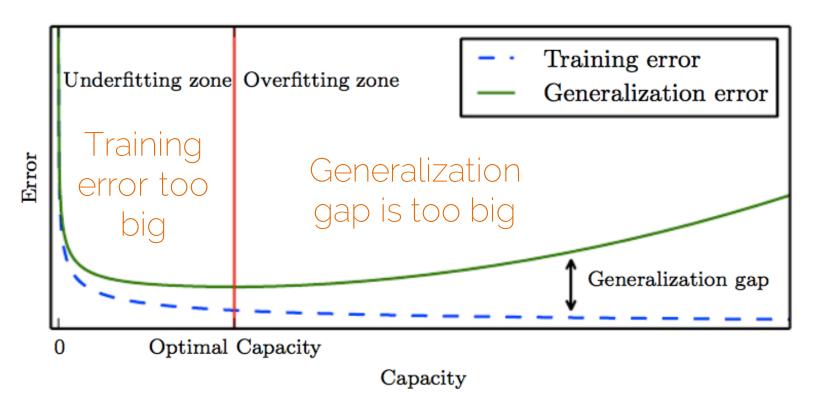
Overfitting and underfitting



What is lambda for each of the cases?

Credits: Deep Learning. Goodfellow et al.

Overfitting and underfitting



Credits: Deep Learning. Goodfellow et al.

Live demo

Next lectures

Thursday 4th May in the Chemistry Building!

Topic: optimization

First exercise on Friday 5th of May here!