

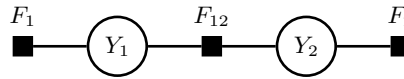
## Weekly Exercise 7

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### Fast Primal-Dual Schema

(6 Points)

**Exercise 1 (Primal-dual LP, 4 Points).** Let us consider the following *factor graph* model with  $\mathcal{Y}_1 = \{1, 2, 3\}$  and  $\mathcal{Y}_2 = \{1, 2\}$



where the factor energies are defined as follows:

$y_1$	$E_1(y_1)$	$y_2$	$E_2(y_2)$	$E_{12}(y_1, y_2)$	1	2
1	5	1	1	1	0	1
2	2	2	2	2	1	0
3	7			3	4	1

Define the **primal** and the **dual linear programs**

$$\begin{array}{ll}
 \min_{\mathbf{x}} \langle \mathbf{c}, \mathbf{x} \rangle & \max_{\mathbf{y}} \langle \mathbf{b}, \mathbf{y} \rangle \\
 \mathbf{Ax} = \mathbf{b} & \mathbf{A}^T \mathbf{y} \leq \mathbf{c} \\
 \mathbf{x} \geq \mathbf{0} &
 \end{array}$$

for the *multi-labeling problem* corresponding to the factor graph above:

$$E(\mathbf{y}) = E_1(y_1) + E_2(y_2) + E_{12}(y_1, y_2) .$$

**Exercise 2 (Complementary slackness, 2 Points).** Let  $(\mathbf{x}, \mathbf{y})$  be a pair of *integral primal* and *dual feasible* solutions to the linear programming relaxation

$$\begin{array}{ll}
 \min_{\mathbf{x}} \langle \mathbf{c}, \mathbf{x} \rangle & \max_{\mathbf{y}} \langle \mathbf{b}, \mathbf{y} \rangle \\
 \mathbf{Ax} = \mathbf{b} & \mathbf{A}^T \mathbf{y} \leq \mathbf{c} \\
 \mathbf{x} \geq \mathbf{0} &
 \end{array}$$

corresponding to the multi-labeling problem. Show that if  $(\mathbf{x}, \mathbf{y})$  satisfies the *relaxed primal complementary slackness conditions*, that is

$$\forall x_j > 0 \quad \Rightarrow \quad \sum_{i=1} a_{ij} y_i \geq \frac{c_j}{\varepsilon_j} ,$$

then  $\mathbf{x}$  is an  $\varepsilon$ -approximation to the *optimal integral solution*  $\mathbf{x}^*$  with  $\varepsilon = \max_j \varepsilon_j$ .

**Programming****(6 Points)**

**Exercise 3 (Semantic image segmentation with  $\alpha$ -expansion, 6 Points).** Consider the energy function

$$E(\mathbf{y}; \mathbf{x}) = \sum_{i \in \mathcal{V}} E_i(y_i; x_i) + w \sum_{i,j \in \mathcal{E}} E_{ij}(y_i, y_j; x_i, x_j) , \quad (1)$$

for the multi-labeling problem, i.e.  $\mathbf{y} \in \mathcal{L}^{\mathcal{V}}$ , where  $\mathcal{L}$  stands for the label set.  $\mathcal{V}$  is the set of pixels and  $\mathcal{E}$  consists of all four-neighboring pixels. Implement the  $\alpha$ -expansion algorithm to solve the **semantic image segmentation** for the images shown in figure 1. Try to choose different  $w$  for Equation (1) and compare the segmentation results.



Figure 1: The test images for semantic image segmentation.

These test images have been obtained from the [MSRC image understanding dataset](https://www.microsoft.com/en-us/research/project/image-understanding/)<sup>1</sup>, which contains 21 classes, i.e.  $\mathcal{L} = \{1, 2, \dots, 21\}$ . The meaning of the classes are given in the `21class.txt` file. Use it to check whether your results are reasonable.

To define the **unary energy functions**  $E_i$ , use the `*.c_unary` files provided in the supplementary material (supp\_07). Each test image has its own unary file, specified by the same filename. From each unary file, you can read out a  $K \times H \times W$  array of float numbers. The  $H$  and  $W$  are the image height and width, and  $K = 21$  is the number of classes. This array contains the 21-class probability distribution for each pixel. You may find the `multilabel_demo.cpp` in the supplementary material, which demonstrates how to load a unary file and read out the corresponding probability values. The unary energy functions  $E_i$  for all  $i \in \mathcal{V}$  are then defined as the *negative log-likelihood*.

The **pairwise energy functions**  $E_{ij}$  are defined by the *contrast sensitive Potts-model*

$$E_{ij}(y_i, y_j; x_i, x_j) = \exp(-\lambda \|x_i - x_j\|^2) \mathbb{I}[y_i \neq y_j] ,$$

where  $x_i$  is the intensity vector for pixel  $i$ , and you may choose  $\lambda = 0.5$ .

<sup>1</sup><https://www.microsoft.com/en-us/research/project/image-understanding/>