

Multiple View Geometry: Exercise Sheet 2

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http://vision.in.tum.de/teaching/ss2019/mvg2019

Exercise: May 22nd, 2019

Part I: Theory

The following exercises should be **solved at home**. You do not have to hand in your solutions, however, writing it down will help you present your answer during the tutorials.

- 1. Which groups have you seen in the lecture? Write down the names and the correct inclusions! (e.g.: group $A \subset \text{group } B$)
- 2. Let A be a symmetric matrix, and λ_a , λ_b eigenvalues with eigenvectors v_a and v_b . Prove: if v_a and v_b are not orthogonal, it follows: $\lambda_a = \lambda_b$.

Hint: What can you say about $\langle Av_a, v_b \rangle$?

3. Let $A \in \mathbb{R}^{n \times n}$ be a symmetric matrix with the orthonormal basis of eigenvectors v_1, \ldots, v_n and eigenvalues $\lambda_1 \geq \ldots \geq \lambda_n$. Find all vectors x, that minimize the following term:

$$\min_{||x||=1} x^{\top} A x$$

How many solutions exist? How can the term be maximized?

Hint: Use the expression $x = \sum_{i=1}^{n} \alpha_i v_i$ with coefficients $\alpha_i \in \mathbb{R}$ and compute appropriate coefficients!

4. Let $A \in \mathbb{R}^{m \times n}$. Prove that $kernel(A) = kernel(A^{\top}A)$.

$$\begin{array}{ll} \textit{Hint:} \; \mathsf{Consider} & \mathsf{a}) \; \; x \in \mathsf{kernel}(A) & \Rightarrow x \in \mathsf{kernel}(A^\top A) \\ & \mathsf{and} & \mathsf{b}) \; \; x \in \mathsf{kernel}(A^\top A) & \Rightarrow x \in \mathsf{kernel}(A). \end{array}$$

5. Singular Value Decomposition (SVD)

Let
$$A = USV^{\top}$$
 be the SVD of A .

- (a) Write down possible dimensions for A, U, S and V.
- (b) What are the similarities and differences between the SVD and the eigenvalue decomposition?
- (c) What do you know about the relationship between U, S, V and the eigenvalues and eigenvectors of $A^{\top}A$ and AA^{\top} ?
- (d) What is the interpretation of the entries in S and what do the entries of S tell us about A?

Part II: Practical Exercises

The Moore-Penrose pseudo-inverse

To solve the linear system Ax = b for an arbitrary (non-quadratic) matrix $A \in \mathbb{R}^{m \times n}$ of rank $r \leq \min(m, n)$, one can define a (generalized) inverse, also called the *Moore-Penrose pseudo-inverse* (compare Chapter 1, last slide).

In this exercise we want to solve the linear system Dx = b with $D \in \mathbb{R}^{m \times 4}$, $b \in \mathbb{R}^m$ a vector whose components are all equal to 1, and $x^* = [4, -3, 2, -1]^T \in \mathbb{R}^4$ should be one possible solution of the linear system, i.e. for any row $[d_1, d_2, d_3, d_4]$ of D:

$$4d_1 - 3d_2 + 2d_3 - d_4 = 1$$

We recall that the set of all possible solutions $S = \{x^* + v \mid v \in \text{kernel}(D)\}$

- 1. Create some data
 - (a) Generate such a D matrix using random values with m=4 rows. (Hint: Use rand to define d_1, d_2, d_3 and set $d_4 = 4d_1 - 3d_2 + 2d_3 - 1$.) In general, rank(D) = 4, hence there is a unique solution.
 - (b) Introduce small errors into the data.
 (Hint: Use eps*rand with eps=1.e-4)
- 2. Find the coefficients x solving the system Dx = b
 - (a) Compute the SVD for the matrix *D*. (Hint: Use svd)
 - (b) Compute the Moore-Penrose pseudo-inverse using the result from (a), and compare it to the output of the MATLAB function pinv.
 - (c) Compute the coefficients x, and compare it to the true solution x^* .
- 3. Repeat the two previous questions, by setting m to a higher value. How the precision is impacted ?
- 4. We assume in the following that m=3, hence we have infinitely many solutions.
 - (a) Solve again the linear system using questions (1) and (2). Thus rank(D) = 3 and dim(kernel(D)) = 1.
 - (b) Use the function null to get a vector $v \in \text{kernel}(D)$. The set of all possible solutions $S = \{x + \lambda v \mid \lambda \in \mathbb{R}\}$
 - (c) According to the last slide of Chapter 1, we know that the following statement hold: $x_{min} = A^+b$ is among all minimizers of $|Ax b|^2$ the one with the smallest norm |x|.

Let $x_{\lambda} = x + \lambda v$. Using the function plot, display the graph of $||x_{\lambda}||$ according to $\lambda \in \{-100, \dots, 100\}$, and observe that the statement indeed hold.