



0: Introduction and Organization

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General Information





Prerequisites

- (Discrete) probability theory.
- (Basic) graph theory.
- Programming experience in Python (or Matlab).
- + Discrete/continuous optimization.
- + Machine learning.
- + Related courses:
 - Computer Vision I & II.
 - Machine Learning for CV.
 - Convex Optimization for CV & ML.





Outline of the Course

Representation

- Bayesian network (directed model);
- Markov network (undirected model);
- Factor graph, Exponential family.

Inference

- Exact inference: variable elimination, message passing;
- Variational inference: mean field, loopy belief propagation;
- Sampling methods: rejection/importance sampling, Gibbs sampling;
- MAP inference: Graph cut, Linear programming relaxation.

Learning

- Maximum likelihood estimation (MLE);
- Partial observation and expectation-maximization (EM) algorithm;
- Structured learning: structured support vector machine (SSVM).
- Further topics (if time permits)
 - Hidden Markov model and Kalman filter;
 - Boltzmann machines and contrastive divergence, etc.





Contact Information

Tao's office: 02.09.061

Yuesong's office: 02.09.039

Zhenzhang's office: 02.09.060

Office hours: Please write an email.

- Lecture: Starts at quarter past; Short break in between.
- Course webpage (where you check out announcements): https://vision.in.tum.de/teaching/ss2019/pgm2019
- Homework: assigned on Monday; hand in on Monday one week after.
- Bonus policy: see the course webpage.
- Submit your programming exercises per email to: pgm-ss19@vision.in.tum.de
- Passcode for accessing course materials: bayesian



What and Why about PGM?



Probabilistic Graphical Model

• Probabilistic graphical model (PGM), or graphical model for short, is a probabilistic model which uses a graph to represent dependencies among its random variables.

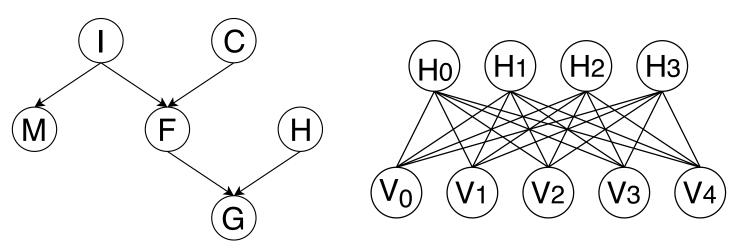


Figure: Examples of graphical models: Bayesian network (left) and Markov network (right).

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Graphical Representation

- Nodes: random variables;
- Edges: interactions;
- Overall graph: joint distribution.

→ Declarative and intuitive graph representation of the probability distribution.

Random variables:

- I: interesting subject?
- C: cool professor?
- M: master thesis?
- F: follow course?
- H: hard work?
- G: good grade?

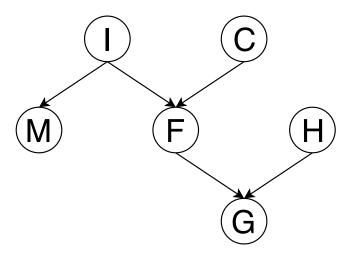


Figure: Corresponding Bayesian network.



Structured Interaction

- Graph structure indicates independence assumptions.
- Example: A binary 28 \times 28 MNIST image $\rightsquigarrow |\mathcal{V}| = 784$ binary RVs:
 - In general: $2^{|\mathcal{V}|} 1 \approx 10^{236}$ free parameters for joint distribution!
 - Full independence: $|\mathcal{V}|$ = **784** free parameters;
 - Grid-structured dependence: $|\mathcal{V}| + |\mathcal{E}| = 2296$ free parameters.

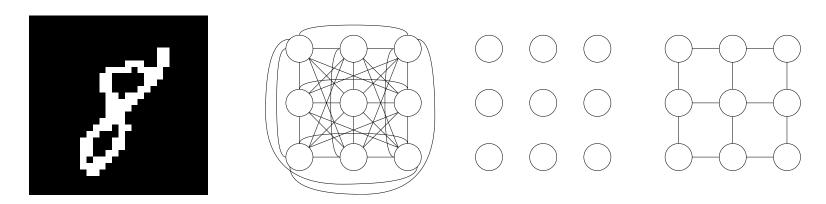


Figure: Binary MNIST image and Markov network with different independence assumptions.

Independence assumptions ↔ Factorization ↔ Tractable modeling



Inference: Reasoning with Uncertainty

- Getting info from graphical models → reasoning with uncertainty!
- Inference process can answer queries like:
 - How likely will I get a good grade: if I Follow the course? if I find the subject Interesting but don't want to work Hard?
 - My friend is Following this course, how likely is the subject Interesting?
 - What are the most probable values for the missing pixels?

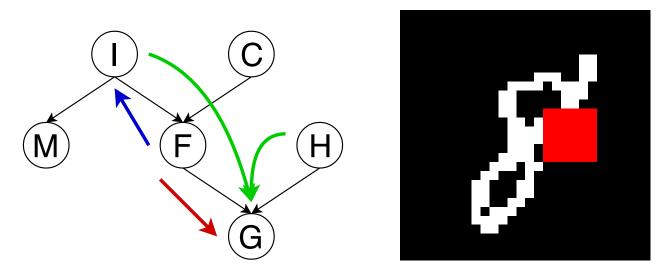


Figure: Illustration of some inference task examples





Learning: Data-driven Model Design

- Parameters and structure of a graphical model can be set ...
 - manually by human expertise and prior → knowledge engineering
 - automatically trained from observed data → machine learning

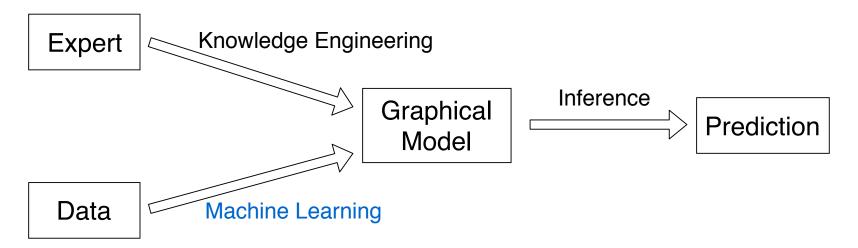


Figure: Design and usage of graphical model.



Applications





Application: Expert System for Medical Diagnosis

Knowledge engineering with Bayesian network.

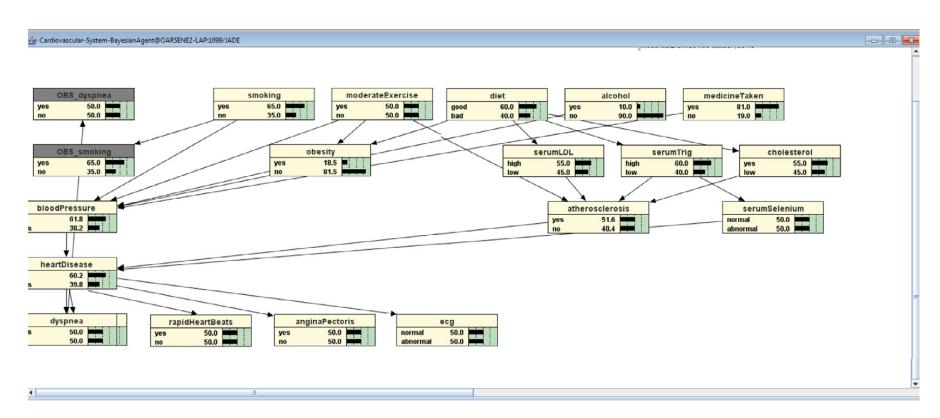


Figure: Illustration of an expert system for medical diagnosis of cardiovascular system¹.

¹Arsene et al., "Expert system for medicine diagnosis using software agents". PGM SS19: 0: Introduction and Organization





Application: Natural Language Processing (NLP)

Modeling sequential data with hidden Markov model.

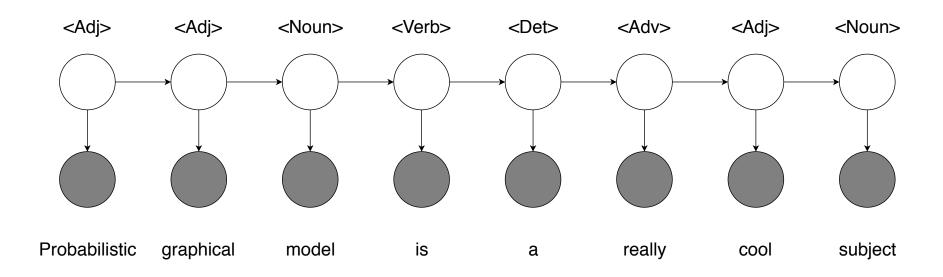


Figure: An example of part-of-speech tagging with hidden Markov model.



Application: Information Theory and Communication

- Probabilistic modeling of noisy communication channel;
- Turbo code, low-density parity check, etc. can be modeled as factor graphs;
- Widely used for communication protocols such as 3G/4G/5G or Wi-Fi.

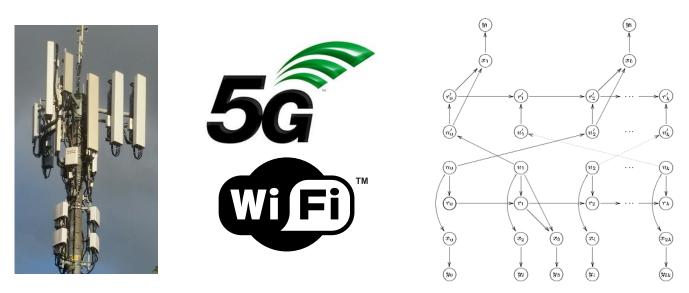


Figure: Telecommunication protocols and illustration of turbo code³⁴.

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²MacKay, Information theory, inference and learning algorithms.

³https://en.wikipedia.org/wiki/Wi-Fi and https://en.wikipedia.org/wiki/5G, accessed on Feb. 20th, 2019.

⁴Lauritzen, "Some modern applications of graphical models".



Application: Statistical Physics

- Modeling with Markov random field.
- Source of inspiration for various inference techniques:
 mean field, simulated annealing, generalized belief propagation, etc.

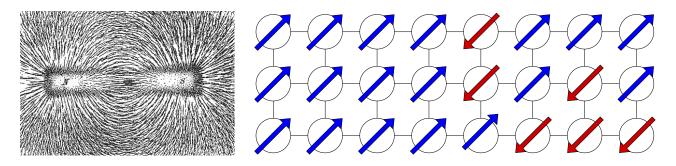


Figure: Illustration of Ising model for ferromagnet, left image from Wikipedia⁵.



Figure: 2D Ising grid at 3 temperatures with (left) or without (right) external magnetic field⁶.

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⁵https://en.wikipedia.org/wiki/Ising_model, accessed on Feb. 20th, 2019.

⁶Generated from https://mattbierbaum.github.io/ising.js/, accessed on Feb. 20th, 2019.





Application: Traffic Modeling and Estimation

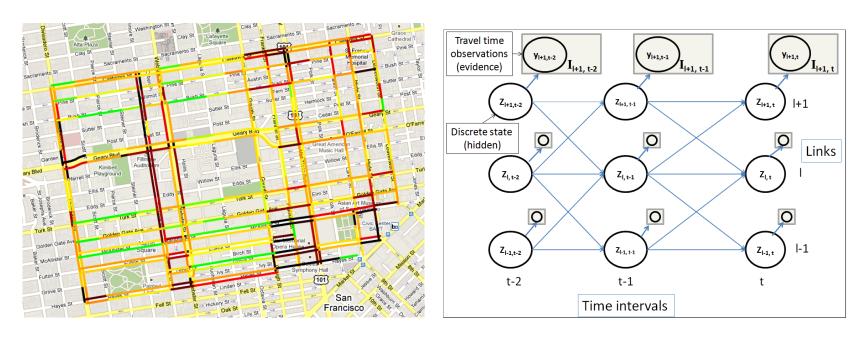


Figure: Traffic modeling and estimation with the help of coupled hidden Markov model⁷.

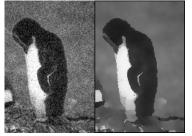
⁷Herring, "Real-time traffic modeling and estimation with streaming probe data using machine learning". PGM SS19: 0: Introduction and Organization



Applications in Computer Vision

- Image data can be represented by Markov random field.
- Graphical model has been applied to a variety of vision tasks:





Optical flow



Stereo matching



Inpainting



Super-resolution



Figure: Various examples of computer vision tasks handled by graphical model⁸.

⁸Felzenszwalb and Huttenlocher, "Efficient belief propagation for early vision"; Levin et al., "Learning how to inpaint from global image statistics"; Tappen et al., "Efficient graphical models for processing images". PGM SS19: 0: Introduction and Organization



Application in CV: Odometry and SLAM

A classic algorithm for odometry and navigation: (extended) Kalman filter.



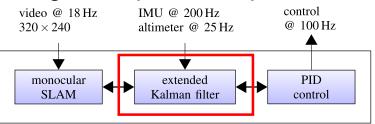


Figure: Extended Kalman filter for navigation of quadrocopter⁹.

• Useful for modeling sequential data in general (e.g. sensor fusion).

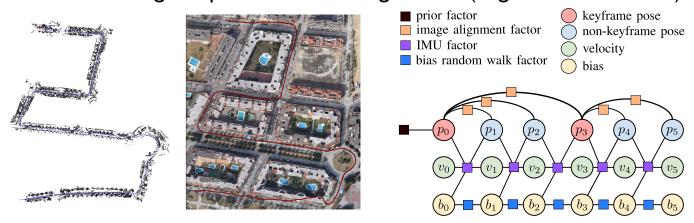


Figure: Factor graph representing the visual-inertial odometry optimization problem¹⁰.

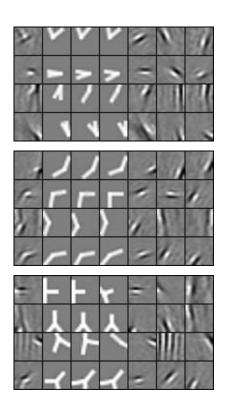
⁹Engel et al., "Camera-Based Navigation of a Low-Cost Quadrocopter".

¹⁰Usenko et al., "Direct Visual-Inertial Odometry with Stereo Cameras". PGM SS19: 0: Introduction and Organization



More applications in CV

(i) Generative modeling; (ii) Structured prediction.



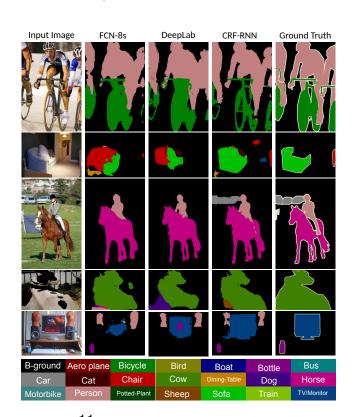


Figure: Graphical model for unsupervised learning¹¹ (left) and semantic segmentation¹² (right).

¹¹Lee et al., "Sparse Deep Belief Net Model for Visual Area V2".

¹²Zheng et al., "Conditional Random Fields As Recurrent Neural Networks". PGM SS19: 0: Introduction and Organization