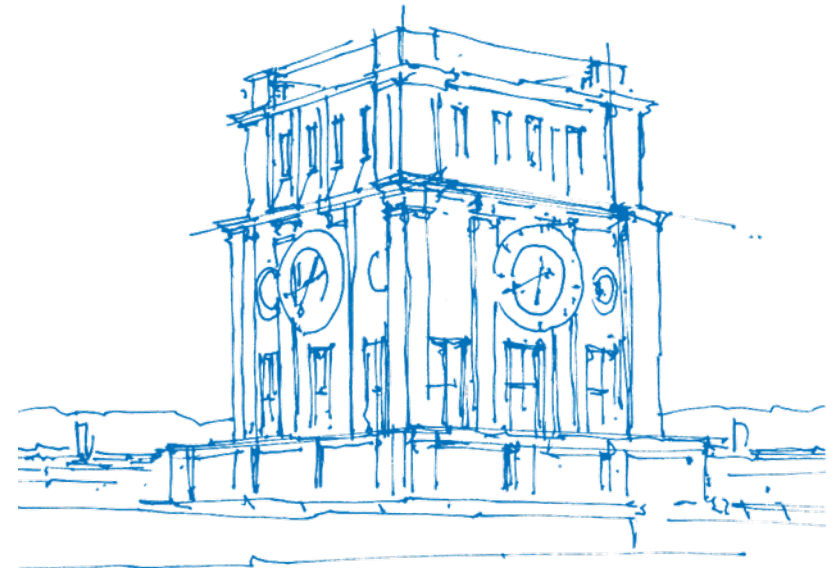




# III : Inference on Graphical Models

Tao Wu, Yuesong Shen, Zhenzhang Ye

Computer Vision & Artificial Intelligence  
Technical University of Munich

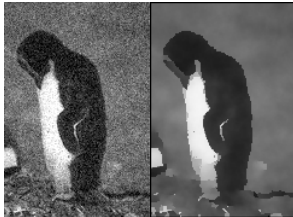


*TUM Uhrenturm*

# Motivation

- Many computer vision tasks boil down to inference on graphical models.

**Denoising**



**Optical flow**



**Stereo matching**



**Inpainting**



**Super-resolution**



1. **Probabilistic inference:** compute marginal distribution

$$p(y) = \sum_x p(y, x).$$

2. **MAP inference:** compute maximum of conditional distribution

$$\arg \max_y p(y|x).$$



# Exact Inference



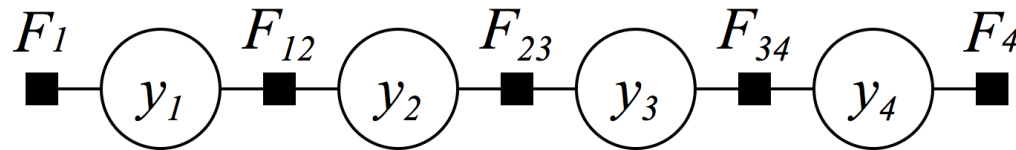
# Outline of the Section

- Basic idea: Variable elimination.
- Junction tree algorithm on arbitrary MRFs.
- Belief propagation on tree factor graphs.

# Example: Marginal Query on a "Chain" MRF

Joint distribution represented by MRF:

$$p(y_1, y_2, y_3, y_4) = \frac{1}{Z} \phi_1(y_1) \cdot \phi_{12}(y_1, y_2) \cdot \phi_{23}(y_2, y_3) \cdot \phi_{34}(y_3, y_4) \cdot \phi_4(y_4).$$



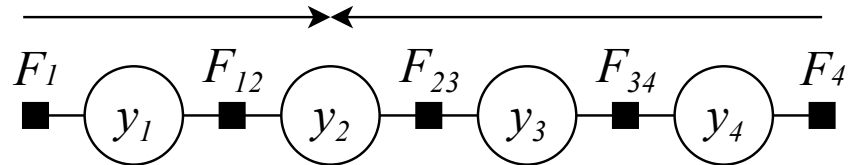
Query about marginal distribution  $p(y_2) = ?$

# Variable Elimination

Apply **variable elimination** (VE) to the marginal query:

$$\begin{aligned} p(y_2) &= \sum_{y_1, y_3, y_4} p(y_1, y_2, y_3, y_4) \\ &= \sum_{y_1, y_3, y_4} \frac{1}{Z} \phi_1(y_1) \phi_{12}(y_1, y_2) \phi_{23}(y_2, y_3) \phi_{34}(y_3, y_4) \phi_4(y_4) \\ &= \frac{1}{Z} \underbrace{\sum_{y_1} \left( \phi_1(y_1) \phi_{12}(y_1, y_2) \right)}_{=: m_{1 \rightarrow 2}(y_2)} \sum_{y_3} \left( \phi_{23}(y_2, y_3) \underbrace{\sum_{y_4} \left( \phi_{34}(y_3, y_4) \phi_4(y_4) \right)}_{=: m_{4 \rightarrow 3}(y_3)} \right) \\ &= \frac{1}{Z} m_{1 \rightarrow 2}(y_2) \underbrace{\sum_{y_3} \left( \phi_{23}(y_2, y_3) m_{4 \rightarrow 3}(y_3) \right)}_{=: m_{3 \rightarrow 2}(y_2)} \\ &= \frac{1}{Z} m_{1 \rightarrow 2}(y_2) m_{3 \rightarrow 2}(y_2), \\ Z &= \sum_{y_2} m_{1 \rightarrow 2}(y_2) m_{3 \rightarrow 2}(y_2). \end{aligned}$$

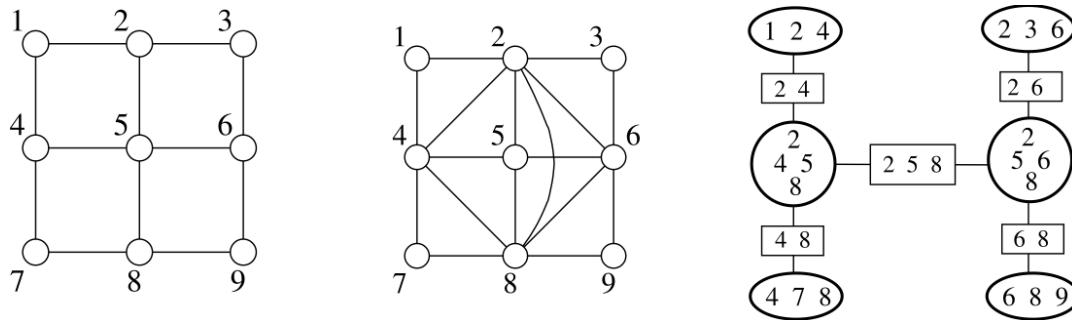
# Variable Elimination



- This algorithm is called **sum-product** VE.
- Sum-product VE yields *exact* inference (of one node marginal) on any *tree-structured factor graph*.
- A similar algorithm can be derived for MAP inference – simply switch all "sum" to "max". The resulting algorithm is called **max-product** VE.
- We shall consider two different extensions beyond VE:
  1. Inference on arbitrary MRFs?  $\rightsquigarrow$  **Junction tree algorithm**.
  2. Compute all node/factor marginals at one shot?  $\rightsquigarrow$  **Belief propagation**.

# Junction Tree

- For an undirected graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ , the **junction tree** of  $\mathcal{G}$  is a tree  $\mathcal{T}$  s.t.
  1. The nodes of  $\mathcal{T}$  consist of the *maximal cliques* of  $\mathcal{G}$ .
  2. The edge  $S_{ij}$  between two nodes  $C_i, C_j$  of  $\mathcal{T}$  (i.e. two maximal cliques of  $\mathcal{G}$ ) is given by  $S_{ij} = C_i \cap C_j$  (known as the *running intersection property*).
- A graph is **triangulated** if every cycle of length  $\geq 4$  has a *chord*. (A chord is an edge that is not part of the cycle but connects two vertices of the cycle.)
- Theorem [Lauritzen '96]: A graph has a junction tree iff it is triangulated.

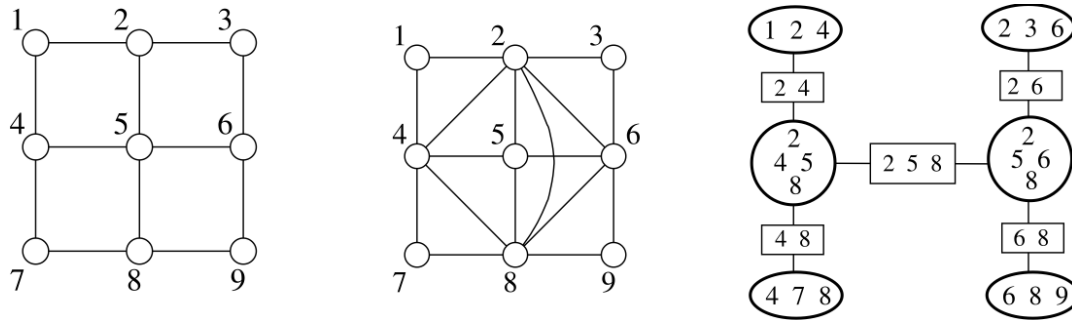


**Figure:**<sup>1</sup> (a) Original graph; (b) Triangulated graph; (c) Junction tree for the graph in (b).

<sup>1</sup>Wainwright and Jordan, “Graphical Models, Exponential Families, and Variational Inference”.



# Junction Tree Algorithm



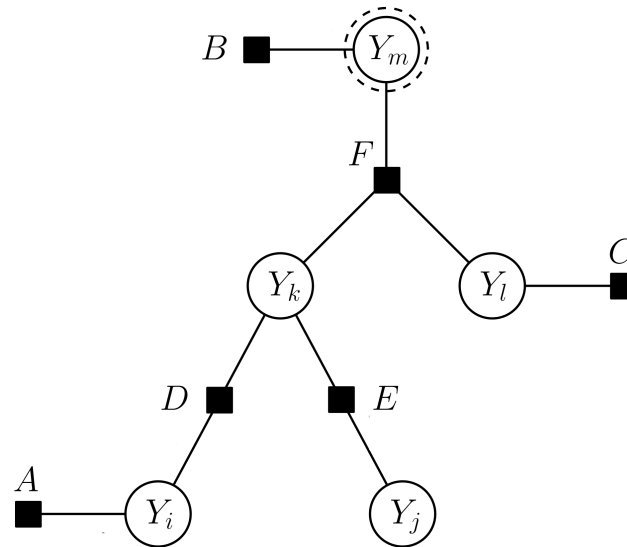
Sum-product message passing on a junction tree  $\mathcal{T}$  appears like:

$$m_{C_i \rightarrow C_j}(y_{C_j \setminus C_i}) = \sum_{y_{C_i \setminus C_j}} \psi_{C_i}(y_{C_i}) \prod_{C_k \in \mathcal{N}_{\mathcal{T}}(C_i) \setminus \{C_j\}} m_{C_k \rightarrow C_i}(y_{C_i \setminus C_k}).$$

Overall **junction tree algorithm** for exact inference on an arbitrary MRF:

1. Given an MRF with cycles, triangulate it by adding edges as necessary.
2. Form a junction tree  $\mathcal{T}$  for the triangulated MRF.
3. Run VE on the junction tree  $\mathcal{T}$ .

# Belief Propagation on Tree Factor Graphs<sup>2</sup>



- Factor graph  $\mathcal{G} = (\mathcal{V}, \mathcal{F}, \mathcal{E})$ : assumed to be a tree.
- Neighbors of a variable or factor node:

$$\mathcal{N}_{\mathcal{G}}(i) = \{F \in \mathcal{F} : (i, F) \in \mathcal{E}\},$$

$$\mathcal{N}_{\mathcal{G}}(F) = \{i \in \mathcal{V} : (i, F) \in \mathcal{E}\}.$$

- (Log-domain) energies:  $E_F(y_F) = -\log \phi_F(y_F)$ .

<sup>2</sup>Illustrations for BP are extracted from [Nowozin/Lampert '11].  
 PGM SS19 : III : Inference on Graphical Models

# BP: Leaf-to-Root Stage

0. Pick  $Y_r \in \mathcal{V}$  as the tree root (e.g.  $Y_m$  in the figure).

1a. Schedule the leaf-to-root messages.

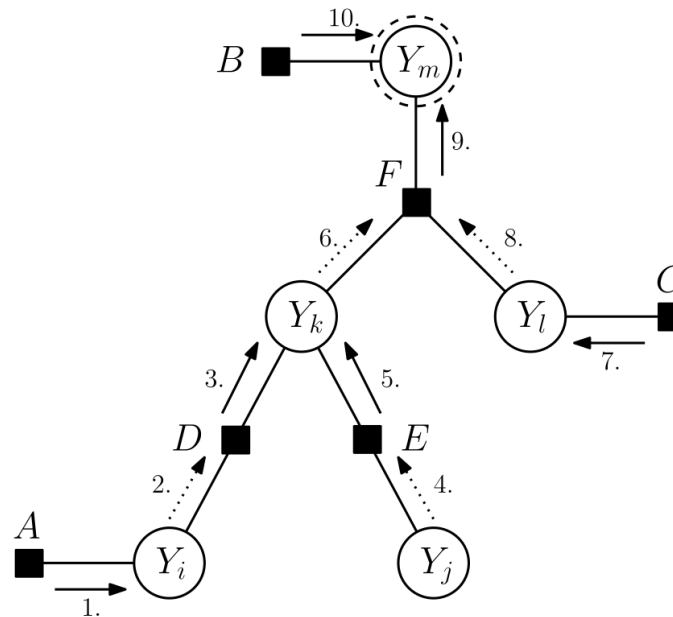


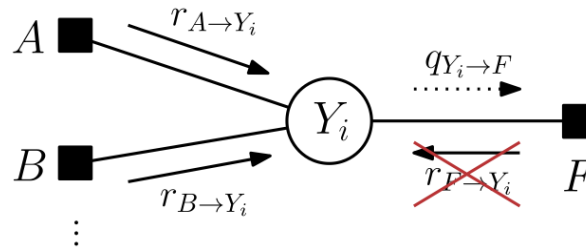
Figure: Belief propagation: leaf-to-root stage.

1b. Compute all leaf-to-root messages (detailed in the next slide).

# BP: Compute Messages

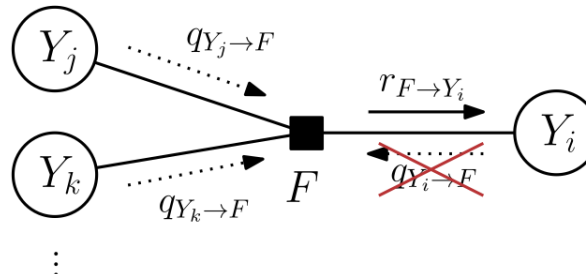
- Compute variable-to-factor message:

$$q_{i \rightarrow F}(y_i) = \sum_{F' \in \mathcal{N}_G(i) \setminus \{F\}} r_{F' \rightarrow i}(y_i).$$



- Compute factor-to-variable message:

$$r_{F \rightarrow i}(y_i) = \log \sum_{Y_F \setminus \{i\}} \exp \left( - E_F(y_F) + \sum_{i' \in \mathcal{N}_G(F) \setminus \{i\}} q_{i' \rightarrow F}(y_F) \right).$$



# BP: Compute the Partition Function

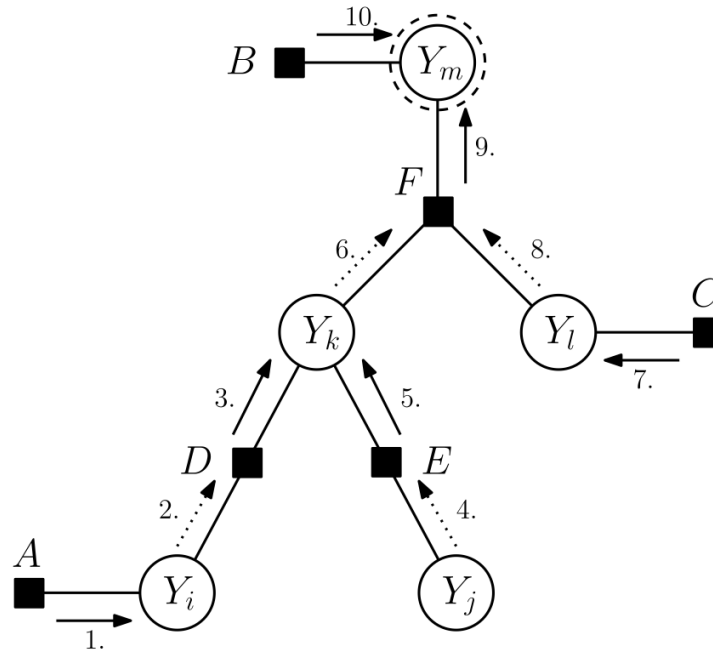


Figure: Belief propagation: leaf-to-root stage.

1c. Compute the log partition function:

$$\log Z = \log \sum_{y_r} \exp \left( \sum_{F \in \mathcal{N}_G(r)} r_{F \rightarrow r}(y_r) \right).$$

# BP: Root-to-Leaf Stage

2a. Schedule the root-to-leaf messages.

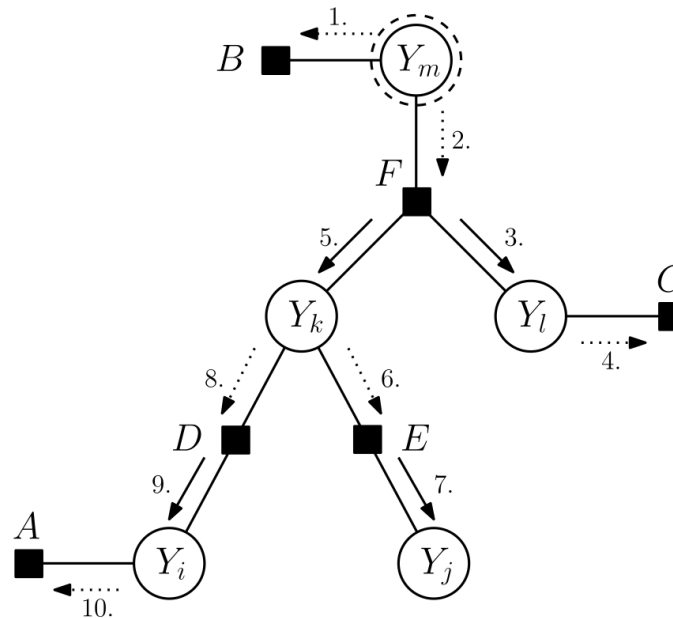


Figure: Belief propagation: root-to-leaf stage.

2b. Compute the root-to-leaf messages using the same formulas on page 12.

# BP: Compute Factor / Variable Marginals

2c. Alongside Step 2b, combine messages and compute factor marginals:

$$\mu_F(y_F) := p(y_F) = \exp \left( - E_F(y_F) + \sum_{i \in \mathcal{N}_G(F)} q_{i \rightarrow F}(y_i) - \log Z \right),$$

as well as variable marginals:

$$\mu_i(y_i) := p(y_i) = \exp \left( \sum_{F \in \mathcal{N}_G(i)} r_{F \rightarrow i}(y_i) - \log Z \right).$$

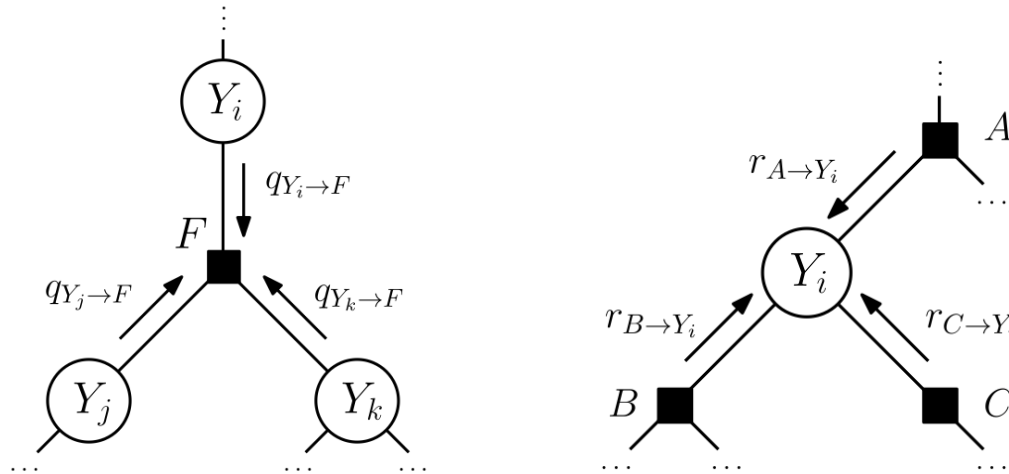


Figure: (left) Factor marginal; (right) Variable marginal.

# BP on Pairwise MRFs

On a pairwise MRF  $\mathcal{H} = (\mathcal{V}, \mathcal{E})$ , the joint distribution is factorized by

$$p(y) = \exp \left( - \sum_{i \in \mathcal{V}} E_i(y_i) - \sum_{(i,j) \in \mathcal{E}} E_{ij}(y_i, y_j) - \log Z \right).$$

BP on such pairwise MRF can be simplified:

- Node-to-node message is computed by

$$m_{i \rightarrow j}(y_j) = \log \sum_{y_i} \exp \left( - E_i(y_i) - E_{ij}(y_i, y_j) + \sum_{k \in \mathcal{N}_{\mathcal{H}}(i) \setminus \{j\}} m_{k \rightarrow i}(y_i) \right).$$

- Node marginal is computed by

$$\mu_i(y_i) = \exp \left( - E_i(y_i) + \sum_{k \in \mathcal{N}_{\mathcal{H}}(i)} m_{k \rightarrow i}(y_i) - \log Z \right).$$





# Further Reading

- Koller & Friedman, Chapters 9, 10.
- Murphy, Chapter 20.
- Nowozin & Lampert, Section 3.1.