## Machine Learning for Robotics and Computer Vision Winter term 2013

Homework Assignment 4 Topic: Boosting Tutorial December 6th, 2013

## Exercise 1: Medusa-Boost

For a model  $y_m(x) = y_{m-1}(x) + w_m \phi_m(x)$  consider the following loss function:

$$L(t,y) = \frac{1}{\exp(ty_{m-1})}\log(1 + \exp((-tw\phi(x))))$$

where log denotes the natural logarithm. What are the optimal new basis function  $\phi_m$  and its corresponding weight  $w_n$ ?

## Exercise 2: Comitee

Consider a regression problem in which we are trying to predict the value of a single continuous variable. Some training process gives us a set of predictive models  $y_m(x)$  where  $m = 1, \ldots, M$ . A comitee prediction can be obtained via

$$y_{\rm com} = \sum_{m=1}^{M} \alpha_m y_m(x)$$

Note that although  $\alpha_m = \alpha$  being constant seems natural, but implies the assumption, that the individual models are uncorrelated. Still we want to restrict the model to ensure that  $y_{\text{com}}$  should neither vote less than nor more than all of its members:

$$y_{\min}(x) \le y_{\max}(x) \le y_{\max}(x)$$

Show that this is equivalent to

$$\alpha_m \ge 0, \quad \sum_{m=1}^M \alpha_m = 1$$

## **Exercise 3: Programming**

Download the file 'ClassCode2.tgz' available at the course's website. Have a look into the file *classification/adaboost.cc* were you find an implementation of the AdaBoost algorithm with decision stumps as weak classifiers.

Compile the project and run *adaboost* with the number of weak classifiers as input parameter. Generate a plot of the classification error with respect to the number of weak classifiers. What do you observe?