

Variational Methods for Computer Vision: Solution Sheet 5

Exercise: 28 November 2013

Part I: Theory

1. From exercise 1 of sheet 4 we know that the Euler-Lagrange equation of functionals involving

$$\mathcal{L}(u(x), u'(x), u''(x)) \text{ is } \frac{\partial \mathcal{L}}{\partial u} - \frac{d}{dx} \frac{\partial \mathcal{L}}{\partial u'} + \frac{d^2}{dx^2} \frac{\partial \mathcal{L}}{\partial u''}$$

Using this result we get:

$$\begin{aligned} -\frac{d}{ds} \frac{\partial \mathcal{L}}{\partial C_s} + \frac{d^2}{ds^2} \frac{\partial \mathcal{L}}{\partial C_{ss}} &= -\frac{d}{ds} [\alpha(s)C'(s)] + \frac{d^2}{ds^2} [\beta(s)C''(s)] \\ &= -[\alpha'(s)C'(s) + \alpha(s)C''(s)] + \frac{d}{ds} [\beta'(s)C''(s) + \beta(s)C'''(s)] \\ &= -\alpha'(s)C'(s) + \alpha(s)C''(s) + \beta''(s)C''(s) \\ &\quad + \beta'(s)C'''(s) + \beta'(s)C'''(s) + \beta(s)C''''(s) \end{aligned}$$

2. (a)

$$L(C) := \int_0^1 |\dot{C}(s)| ds = \int_0^1 \sqrt{\left(\frac{dx}{dt}\right)^2 \left(\frac{dy}{dt}\right)^2}$$

So:

$$\begin{aligned} \frac{\partial L}{\partial C'} &= \frac{\partial \sqrt{C'(s)^2}}{\partial C'(s)} \\ &= 2C'(s) \frac{1}{2\sqrt{C'(s)^2}} \\ &= \frac{C'(s)}{|C'(s)|} \end{aligned}$$

And:

$$\frac{\partial L}{\partial C} = -ds \frac{C'(s)}{|C'(s)|}$$

(b)

$$\begin{aligned}\int_0^1 |C(m(s))'| ds &= \int_0^1 \left| \frac{dC}{dm} \frac{dm}{ds} \right| ds \\ &= \int_0^1 \left| \frac{dC}{dm} \right| \left| \frac{dm}{ds} \right| ds \\ &= \int_0^1 \left| \frac{dC}{dm} \right| \frac{dm}{ds} ds \\ &= \int_0^1 \left| \frac{dC}{dx} \right| dx\end{aligned}\tag{*}$$

* Using integration by substitution with $x = m(s)$ and $dx = m'(s)ds$