

Variational Methods for Computer Vision: Solution Sheet 2

Exercise: November 11, 2015

Part I: Theory

1.

$$\begin{aligned} ((f * k_1) * k_2)(x, y) &= \int \left(\int k_1(s) f(x-s, y-t) ds \right) k_2(t) dt \\ &= \int \int f(x-s, y-t) k_1(s) k_2(t) ds dt \\ &= \int \int f(x-s, y-t) \frac{1}{2\pi\sigma^2} \exp\left(-\frac{s^2+t^2}{2\sigma^2}\right) ds dt \\ &= \int \int f(x-s, y-t) K(s, t) ds dt \\ &= (f * K)(x, y) \end{aligned}$$

2. (a)

$$\begin{aligned} \nabla \tilde{f}(x) &= \nabla(f \circ R)(x) \\ &= (D_{Rx} f \circ D_x R)^T \\ &= (D_{Rx} f \circ R)^T \\ &= R^T (D_{Rx} f)^T \\ &= R^T \nabla f(Rx) \end{aligned} \tag{1}$$

Thus:

$$\begin{aligned} R \nabla \tilde{f}(x) &= R R^T \nabla f(Rx) \\ &= \nabla f(Rx) \end{aligned}$$

(b)

$$\begin{aligned} \|\nabla \tilde{f}(x)\| &\stackrel{(a)}{=} \|R^T \nabla f(Rx)\| \\ &= \sqrt{\langle R^T \nabla f(Rx), R^T \nabla f(Rx) \rangle} \\ &= \sqrt{\langle \nabla f(Rx), R R^T \nabla f(Rx) \rangle} \\ &= \sqrt{\langle \nabla f(Rx), \nabla f(Rx) \rangle} \\ &= \|\nabla f(Rx)\| \end{aligned}$$

(c)

$$\begin{aligned} \Delta \tilde{f}(x) &= \operatorname{div} \left(\underbrace{\nabla \tilde{f}(x)}_{R^T \nabla f(Rx)} \right) \\ &= \operatorname{div} \begin{pmatrix} \cos(\alpha) f_x + \sin(\alpha) f_y \\ -\sin(\alpha) f_x + \cos(\alpha) f_y \end{pmatrix} = \tilde{f}_{xx} + \tilde{f}_{yy} \end{aligned}$$

Thus:

$$\begin{aligned}\tilde{f}_{xx} &= \partial_x (\cos(\alpha)f_x + \sin(\alpha)f_y) \\ &= \partial_x \cos(\alpha)f_x + \partial_x \sin(\alpha)f_y \\ &= \cos^2(\alpha)f_{xx} + \cos(\alpha)\sin(\alpha)f_{xy} + \cos(\alpha)\sin(\alpha)f_{yx} + \sin^2(\alpha)f_{yy}\end{aligned}$$

And:

$$\begin{aligned}\tilde{f}_{yy} &= \partial_y (-\sin(\alpha)f_x + \cos(\alpha)f_y) \\ &= \sin^2(\alpha)f_{xx} - \cos(\alpha)\sin(\alpha)f_{xy} - \cos(\alpha)\sin(\alpha)f_{yx} + \cos^2(\alpha)f_{yy}\end{aligned}$$

Therefore:

$$\begin{aligned}\tilde{f}_{xx} + \tilde{f}_{yy} &= f_{yy} \underbrace{(\sin^2(\alpha) + \cos^2(\alpha))}_{=1} + f_{xx} \underbrace{(\sin^2(\alpha) + \cos^2(\alpha))}_{=1} \\ &= \Delta(f(Rx))\end{aligned}$$

3. (a)

$$\begin{aligned}\operatorname{div}(g \cdot \nabla u)(x) &= g \operatorname{div}(\nabla u)(x) \\ &= g \Delta u(x)\end{aligned}$$

(b)

$$\begin{aligned}\operatorname{div}(g \nabla u)(x) &= \frac{\partial}{\partial x_1} \left(g \frac{\partial}{\partial x_1} u \right)(x) + \frac{\partial}{\partial x_2} \left(g \frac{\partial}{\partial x_2} u \right)(x) \\ &= \frac{\partial^2 u}{\partial x_1^2}(x)g(x) + \frac{\partial^2 u}{\partial x_2^2}(x)g(x) + \frac{\partial g}{\partial x_1}(x) \frac{\partial u}{\partial x_1}(x) + \frac{\partial g}{\partial x_2}(x) \frac{\partial u}{\partial x_2}(x) \\ &= g(x) \Delta u(x) + \langle \nabla g(x), \nabla u(x) \rangle\end{aligned}$$