



Machine Learning for Applications in Computer Vision

Neural Networks and Deep Learning

Philip Häusser

Recap: What is Learning?

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- problem ("classification")
- data (images + labels)
- model (linear regression)
- cost function
- optimization algorithm



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What is "Deep"?

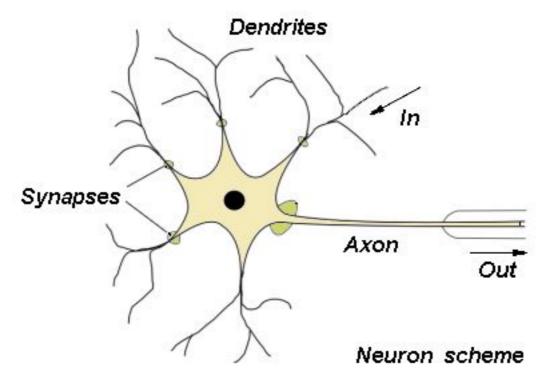
Recap: What is Learning?

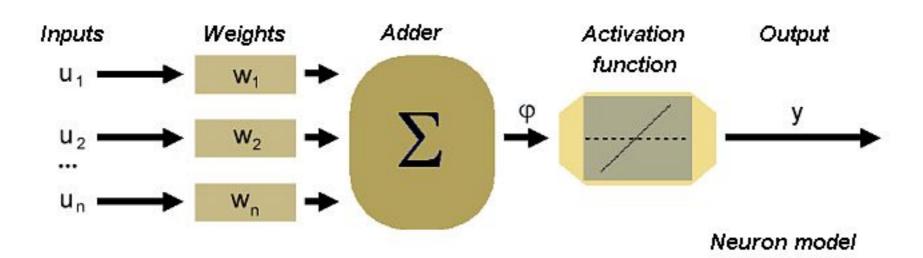
- problem ("classification")
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What is "Deep"?

Perceptron

• The human brain (10¹⁰ cells) is the archetype of neural networks





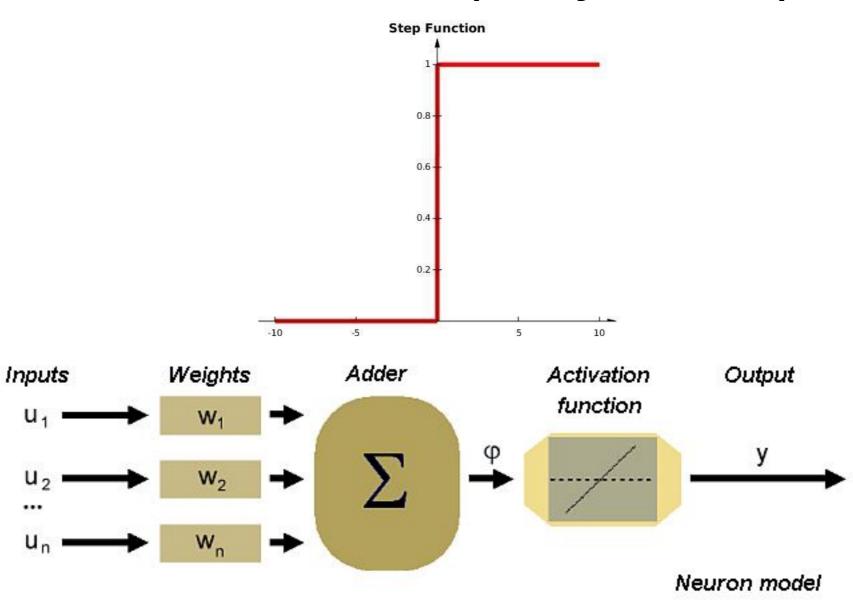
http://home.agh.edu.pl/~vlsi/Al/intro/



Neuron Activations

Different type of activation functions

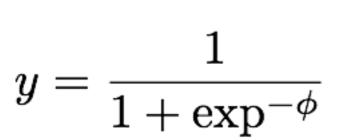
Threshold activation (binary classifier)

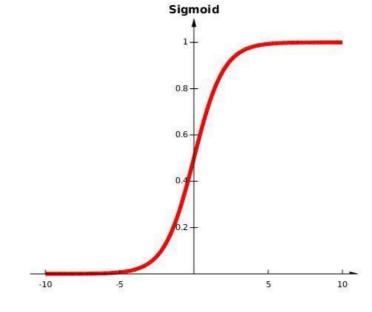


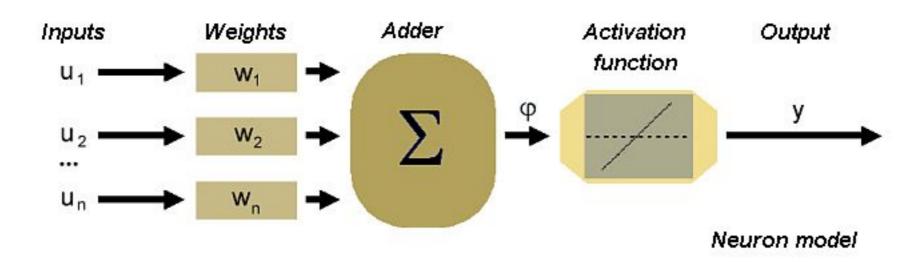
Neuron Activations

Different type of activation functions

Sigmoid activation



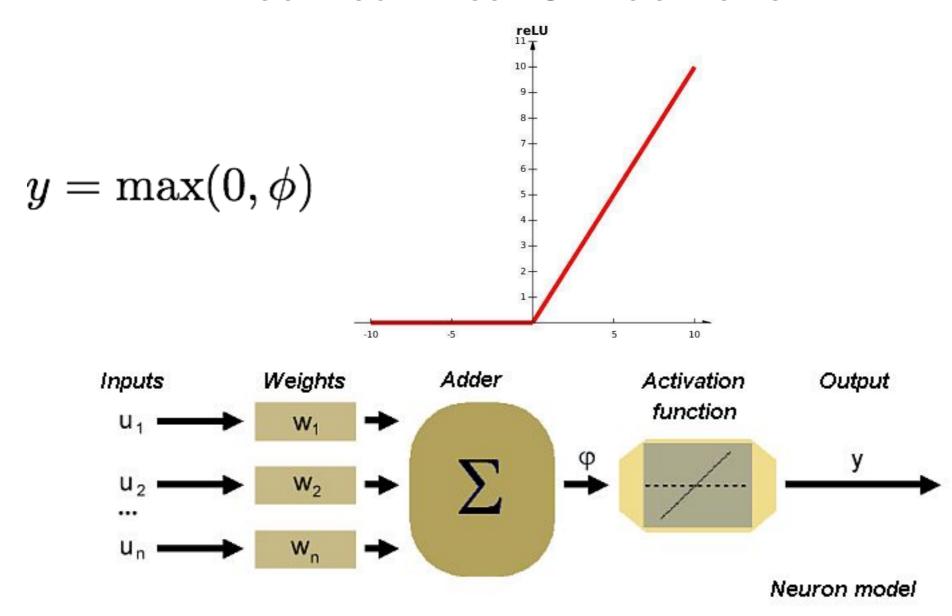




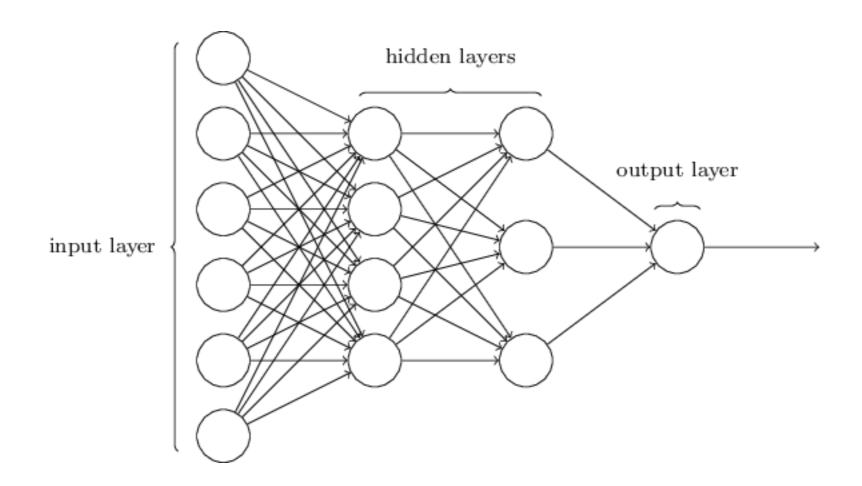
Neuron Activations

Different type of activation functions

rectified Linear Unit activation

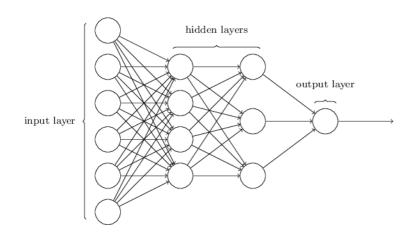


Simple Neural Network



• good reference: <u>neuralnetworksanddeeplearning.com</u>

Simple Neural Network

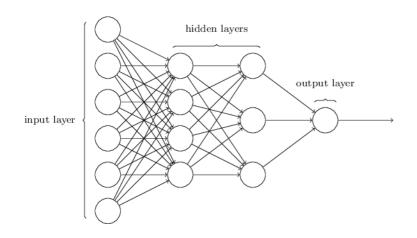


Why is it good?

- inspired by brain
- highly non-linear → function approximator
- shown to solve complicated tasks successfully
- "self-organizing map" / parameters are learned
- data driven



Simple Neural Network



Why is it bad?

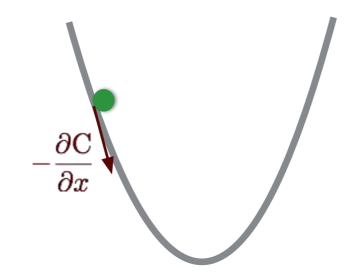
- inspired by brain
- highly non-linear
- high degree of freedom
- shown to solve complicated tasks successfully
- "self-organizing map"
 - → parameters are learned
- data driven
- not much theory yet



Define a cost function

prediction ground truth
$$C(w,b) \equiv rac{1}{2n} \sum_x \|y(x) - a\|^2$$

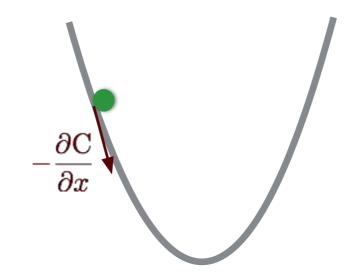
Goal: Find global minimum



Define a cost function

prediction ground truth
$$C(w,b) \equiv rac{1}{2n} \sum_x \|y(x) - a\|^2$$

Goal: Find global minimum



Gradient Descent

Define a cost function

$$C(w,b) \equiv rac{1}{2n} \sum_{x} \|y(x) - a\|^2$$

Minimize the error (derivative of the cost) with gradient descent
 Gradient descent update rule:

$$w_k \to w'_k = w_k - \eta \frac{\partial C}{\partial w_k}$$
$$b_l \to b'_l = b_l - \eta \frac{\partial C}{\partial b_l}$$

Learning rate





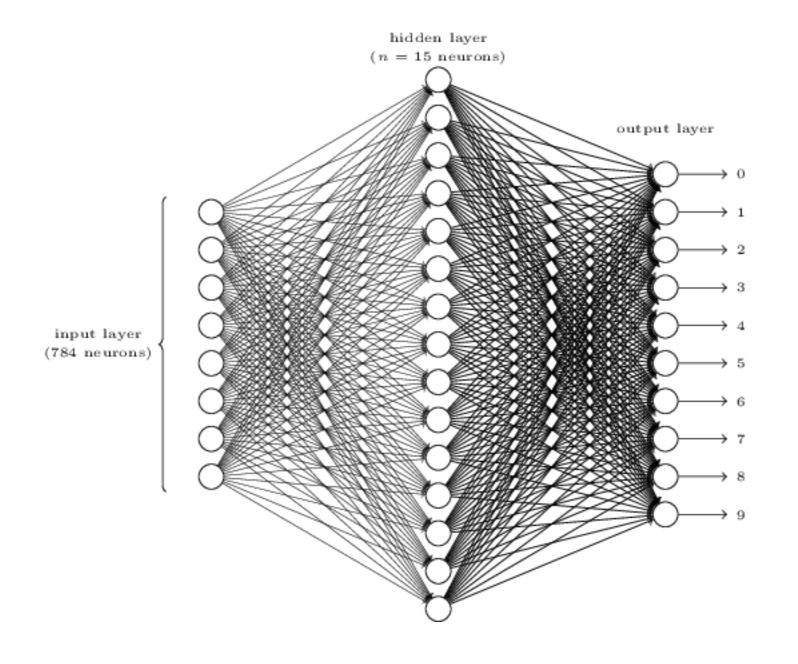
Define a cost function

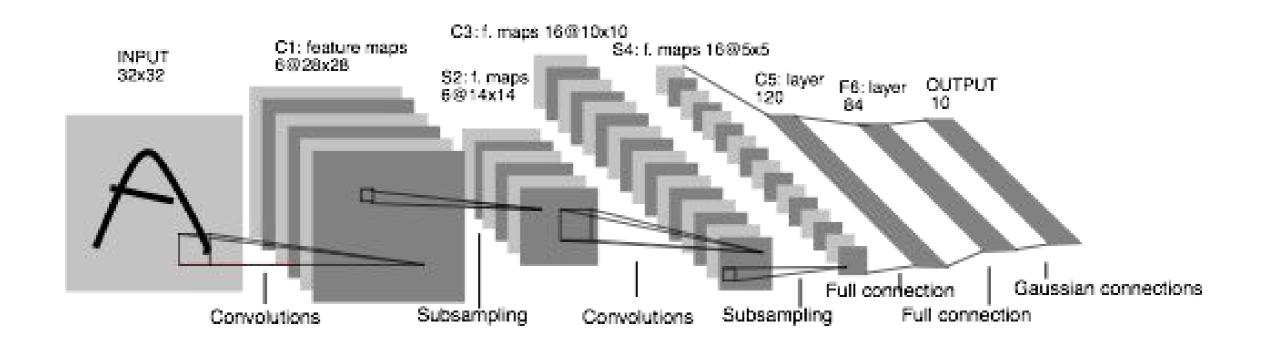
prediction ground truth
$$C(w,b) \equiv rac{1}{2n} \sum_x \|y(x) - a\|^2$$

- Propagate the error through layers
 - Take the derivative of the output of the layer w.r.t the input of the layer
 - Apply update rule for the parameters

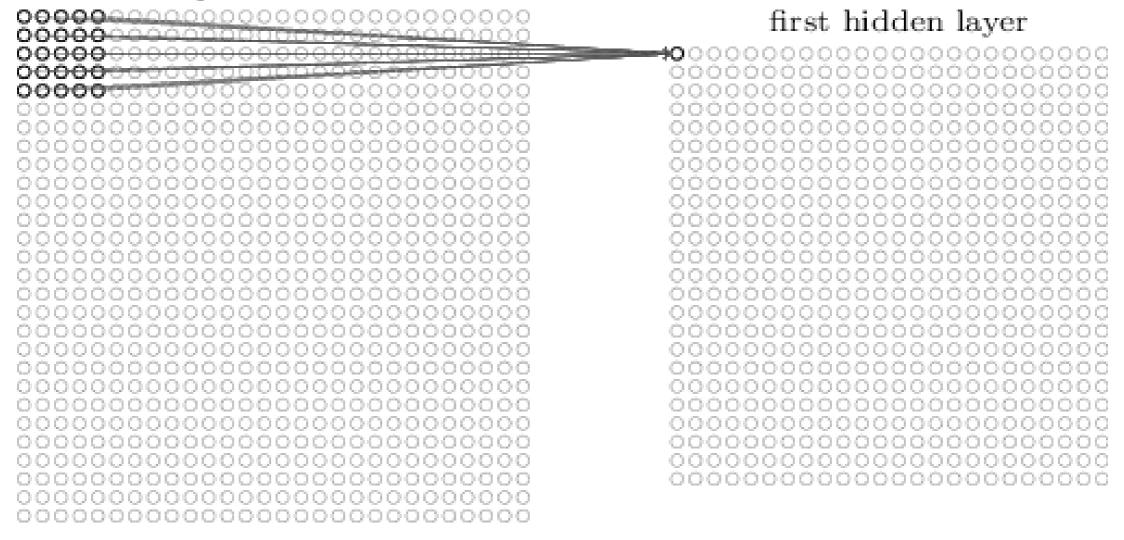


MNIST Digit Classification with NN



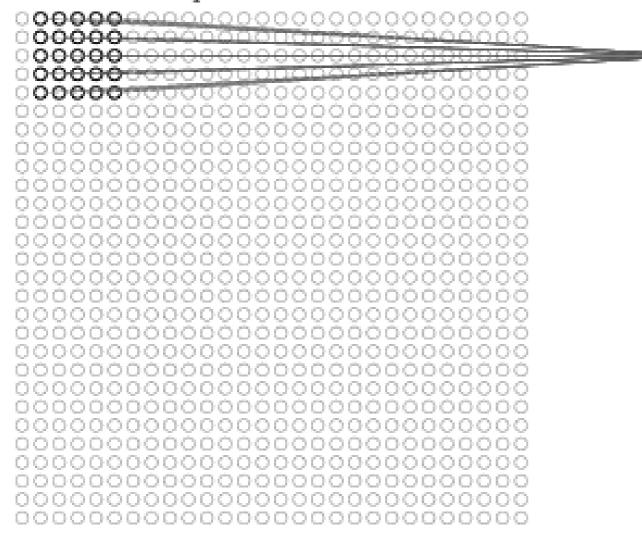


input neurons

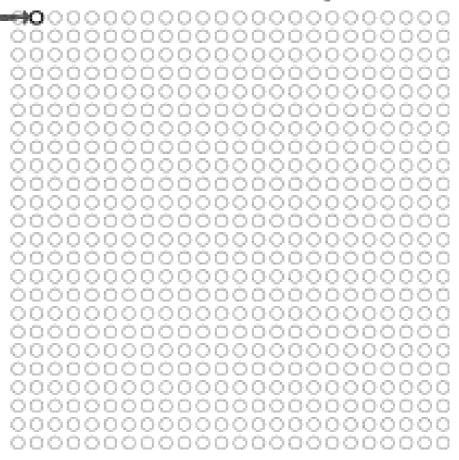


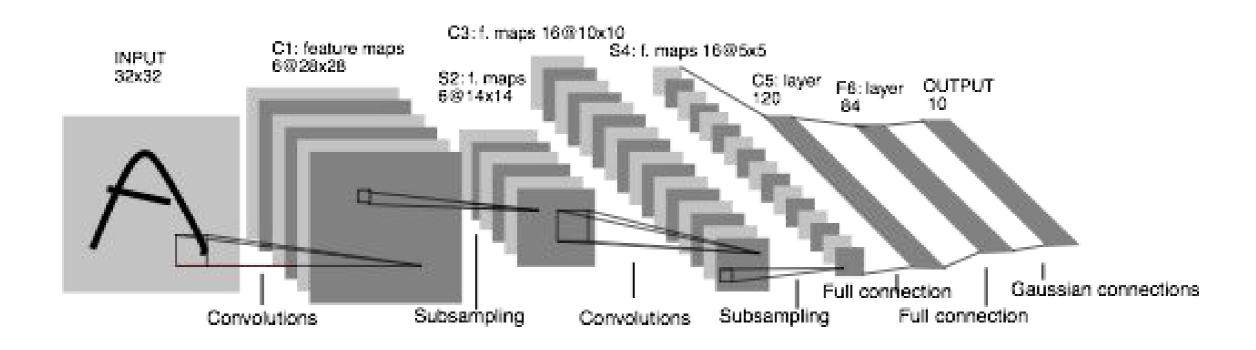


input neurons



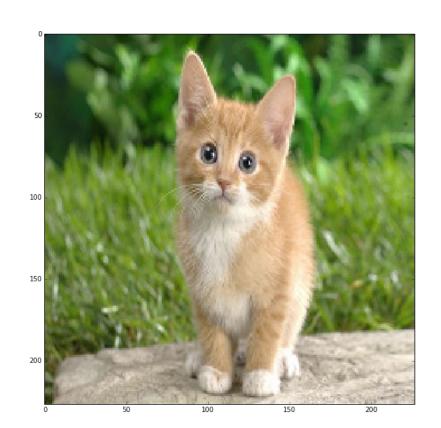
first hidden layer

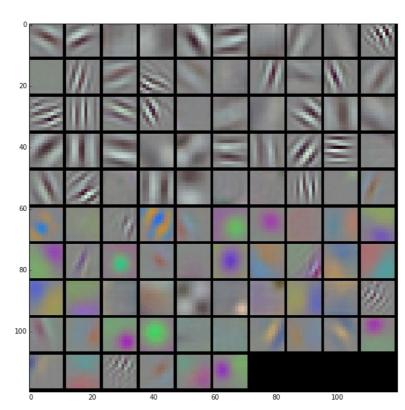


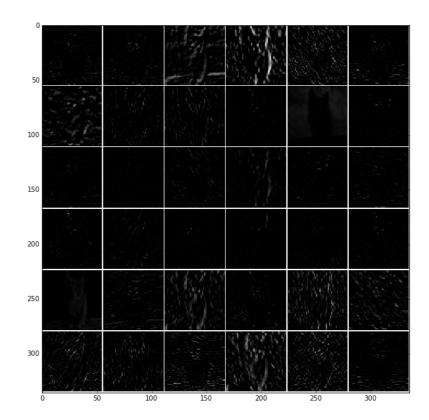


Machine Learning for

Computer Vision







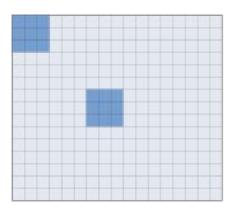
AlexNet

Krizhevsky, Alex, Ilya Sutskever, and Geoffrey E. Hinton. "Imagenet classification with deep convolutional neural networks."

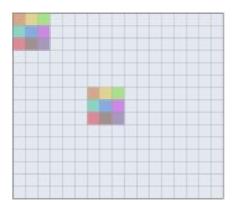
Advances in neural information processing systems. 2012.

Convolutional networks take advantage of the properties of natural signals:

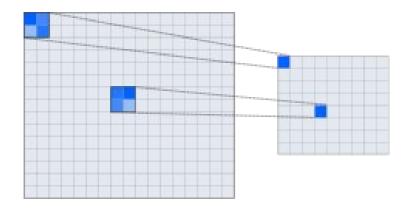
local connections



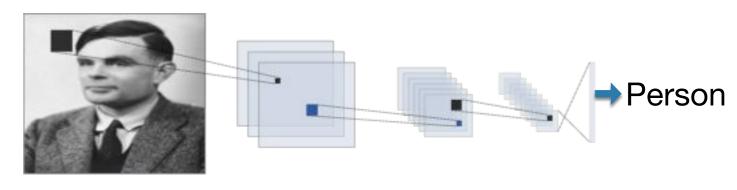
shared weights



pooling

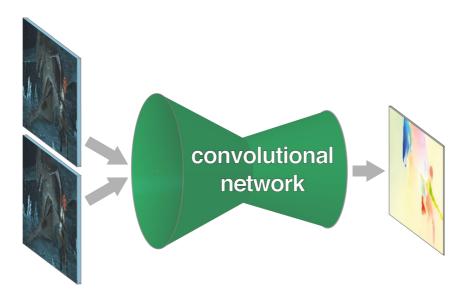


the use of many layers



FlowNet: Learning Optical Flow with Convolutional Networks

Philipp Fischer, Alexey Dosovitskiy, Eddy Ilg, Thomas Brox Philip Häusser, Caner Hazırbaş, Vladimir Golkov, Daniel Cremers, Patrick van der Smagt

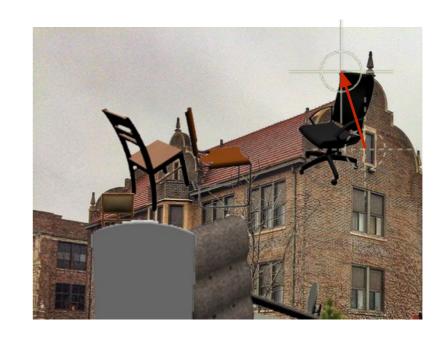




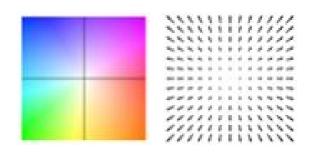


Flying Chairs









Data Augmentation











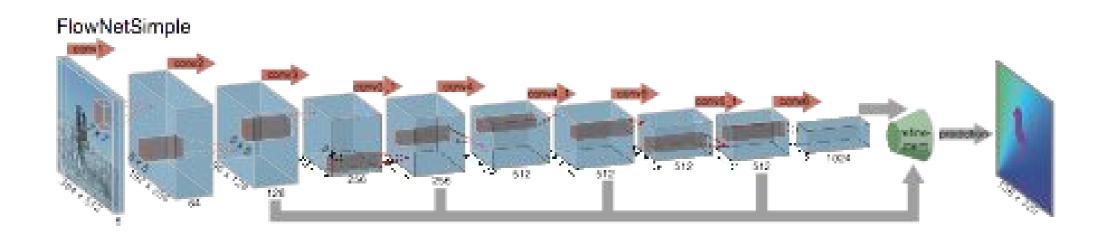


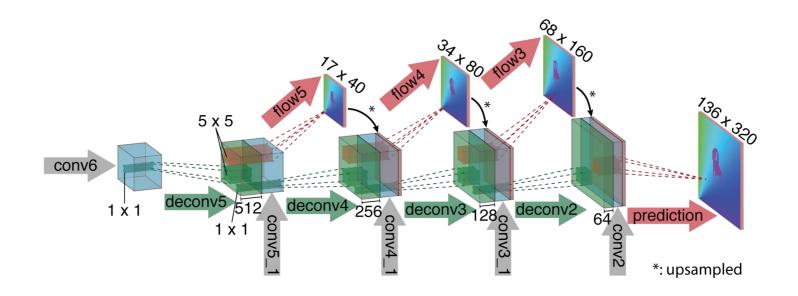
- translation, rotation, scaling, additive Gaussian noise
- changes in brightness, contrast, gamma and colour





FlowNetSimple

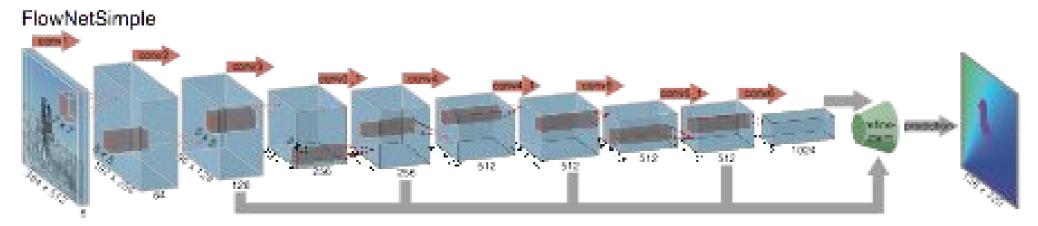




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FlowNetSimple - Flying Chairs









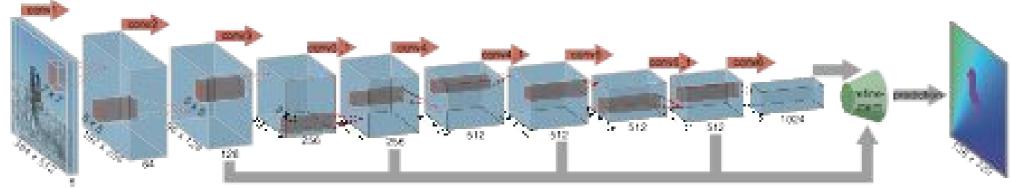
Philip Haeusser

Computer Vision Group

FlowNetSimple - Sintel

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FlowNetSimple











FlowNetSimple + Variational Smoothing













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P. Fischer, A. Dosovitskiy, E. Ilg, P. Häusser, C. Hazırbas, V. Golkov P. v.d. Smagt, D. Cremers, T. Brox

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