

Conference and Workshop Papers

- [C1] M Gladkova, R Wang, N Zeller and D Cremers,
Tight Integration of Feature-based Relocalization in Monocular Direct Visual Odometry,
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- [C2] X. Gao, R. Wang, N. Demmel and D. Cremers,
LDSO: Direct Sparse Odometry with Loop Closure,
International Conference on Intelligent Robots and Systems (IROS), October 2018.